Gamma Belief Networks

Mingyuan Zhou

IROM Department, McCombs School of Business The University of Texas at Austin

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Deep learning

- There is significant recent interest in deep learning due to its excellent performance in large-scale real applications, such as image classification and speech recognition.
- State-of-the-art results in supervised learning when the labeled data are abundant.
- Multilayer generative models for nonlinear distributed representations:
 - SBN, sigmoid belief network
 - DBN, deep belief network (a SBN whose last layer is replaced with a restricted Boltzmann machine that is undirected)
 - DBM, deep Boltzmann machine (a hierarchy of restricted Boltzmann machines)

Challenges in deep learning

- The hidden units are often restricted to be binary.
- Difficult to train a deep network in an unsupervised manner.
- A greedy layer-wise training strategy is often used due to the difficulty of jointly training all hidden layers.
- Lack of principled ways to determine the network structure, including the depth (number of layers) of the network and width (number of units) of each of its hidden layers.
- Commonly used deep learning models are not naturally designed for count data.

Our objectives

- Design a multilayer deep model that is well suited for extracting nonlinear distributed representations for high-dimensional sparse count, binary, and nonnegative real vectors.
- Construct the deep network using nonnegative real hidden units rather than using binary ones.
- Using nonparametric Bayesian priors to automatically infer the network structure from the data.

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Figure: An example directed network of five hidden layers, with $K_0 = 8$ visible units, $[K_1, K_2, K_3, K_4, K_5] = [6, 4, 3, 3, 2]$, and sparse connections between the hidden units of adjacent layers.

$$P\left(\mathbf{x}_{j}^{(1)}, \{\boldsymbol{\theta}_{j}^{(t)}\}_{t} \middle| \{\boldsymbol{\Phi}^{(t)}\}_{t}\right) = P\left(\mathbf{x}_{j}^{(1)} \middle| \boldsymbol{\Phi}^{(1)}, \boldsymbol{\theta}_{j}^{(1)}\right) \times \left[\prod_{t=1}^{T-1} P\left(\boldsymbol{\theta}_{j}^{(t)} \middle| \boldsymbol{\Phi}^{(t+1)}, \boldsymbol{\theta}_{j}^{(t+1)}\right)\right] P\left(\boldsymbol{\theta}_{j}^{(T)}\right).$$



Figure: A tree on "religion."

The Poisson gamma belief network (PGBN)

- Assume the observations are multivariate count vectors x⁽¹⁾_j ∈ Z^{K₀}, where Z = {0, 1, ...}.
- ► We construct the PGBN to infer a multilayer deep representation for {x_j⁽¹⁾}_j.
- ▶ With $\mathbf{\Phi}^{(t)} \in \mathbb{R}_{+}^{K_{t-1} \times K_t}$, the generative model of the PGBN with T hidden layers, from the top to bottom, is expressed as

$$\begin{split} \theta_j^{(T)} &\sim \operatorname{Gam}\left(\mathbf{r}, 1/c_j^{(T+1)}\right), \\ & \dots \\ \theta_j^{(t)} &\sim \operatorname{Gam}\left(\mathbf{\Phi}^{(t+1)}\theta_j^{(t+1)}, 1/c_j^{(t+1)}\right), \\ & \dots \\ \mathbf{x}_j^{(1)} &\sim \operatorname{Pois}\left(\mathbf{\Phi}^{(1)}\theta_j^{(1)}\right), \quad \theta_j^{(1)} &\sim \operatorname{Gam}\left(\mathbf{\Phi}^{(2)}\theta_j^{(2)}, p_j^{(2)}/(1-p_j^{(2)})\right). \end{split}$$

- The PGBN factorizes the observed count vectors under the Poisson likelihood into the product of a factor loading matrix and the gamma distributed hidden units of layer one.
- The PGBN factorizes the hidden units of each hidden layer into the product a connection weight matrix and the hidden units of the next layer under the gamma likelihood.
- ► The PGBN with a single hidden layer (i.e., T = 1) reduces to Poisson factor analysis as

$$oldsymbol{x}_j^{(1)} \sim \mathsf{Pois}\left(oldsymbol{\Phi}^{(1)}_joldsymbol{ heta}_j
ight), \hspace{0.2cm} oldsymbol{ heta}_j^{(1)} \sim \mathsf{Gam}\left(oldsymbol{r}, p_j^{(2)}/(1-p_j^{(2)})
ight).$$

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The gamma-negative binomial process can be used to support potentially $K_1 = \infty$ number of factors.

Model likelihood

The joint distribution of the observed counts and gamma hidden units given the network in the PGBN:

$$P\left(\mathbf{x}_{j}^{(1)}, \{\boldsymbol{\theta}_{j}^{(t)}\}_{t} \middle| \{\boldsymbol{\Phi}^{(t)}\}_{t}\right) = P\left(\mathbf{x}_{j}^{(1)} \middle| \boldsymbol{\Phi}^{(1)}, \boldsymbol{\theta}_{j}^{(1)}\right) \\ \times \left[\prod_{t=1}^{T-1} P\left(\boldsymbol{\theta}_{j}^{(t)} \middle| \boldsymbol{\Phi}^{(t+1)}, \boldsymbol{\theta}_{j}^{(t+1)}\right)\right] P\left(\boldsymbol{\theta}_{j}^{(T)}\right).$$

$$P\left(\theta_{vj}^{(t)} \mid \phi_{v:}^{(t+1)}, \theta_{j}^{(t+1)}, c_{j+1}^{(t+1)}\right) = \frac{\left(c_{j+1}^{(t+1)}\right)^{\phi_{v:}^{(t+1)}} \theta_{j}^{(t+1)}}{\Gamma\left(\phi_{v:}^{(t+1)} \theta_{j}^{(t+1)}\right)} \left(\theta_{vj}^{(t)}\right)^{\phi_{v:}^{(t+1)}} \theta_{j}^{(t+1)-1} e^{-c_{j+1}^{(t+1)}} \theta_{vj}^{(t)}$$

The joint distribution of the binary visible and hidden units given the network for the sigmoid belief network:

$$P\left(\theta_{v_{j}}^{(t)}=1 \, \big| \, \phi_{v:}^{(t+1)}, \theta_{j}^{(t+1)}, b_{v}^{(t+1)}\right) = \sigma\left(b_{v}^{(t+1)}+\phi_{v:}^{(t+1)}\theta_{j}^{(t+1)}\right).$$

where $\sigma(x) = 1/(1 + e^{-x})$ denotes the sigmoid function.

Interpreting the structure of the PGBN

Using the law of total expectation, we have

$$\mathbb{E}\left[\mathbf{x}_{j}^{(1)} \mid \boldsymbol{\theta}_{j}^{(t)}, \{\mathbf{\Phi}^{(\ell)}, c_{j}^{(\ell)}\}_{1,t}\right] = \left[\prod_{\ell=1}^{t} \mathbf{\Phi}^{(\ell)}\right] \frac{\boldsymbol{\theta}_{j}^{(t)}}{\prod_{\ell=2}^{t} c_{j}^{(t)}}.$$
$$\mathbb{E}\left[\boldsymbol{\theta}_{j}^{(t)} \mid \{\mathbf{\Phi}^{(\ell)}, c_{j}^{(\ell)}\}_{t+1, T}, \mathbf{r}\right] = \left[\prod_{\ell=t+1}^{T} \mathbf{\Phi}^{(\ell)}\right] \frac{\mathbf{r}}{\prod_{\ell=t+1}^{T+1} c_{j}^{(\ell)}}.$$

- Consider $\prod_{\ell=1}^{t} \mathbf{\Phi}^{(\ell)}$ as the K_t topics/factors/nodes of layer $t \in \{1, \ldots, T\}$ and use $\mathbf{r}^{(t)} := \left[\prod_{\ell=t+1}^{T} \mathbf{\Phi}^{(\ell)}\right] \mathbf{r}$ to rank them.
- Consider φ^(t)_{k'k} = Φ^(t)(k', k) as the weight that connects node k of layer t and node k' of layer t − 1.
- Our intuition is that examining the topics/factors from the top to bottom layers will gradually reveal less general and more specific aspects of the data.

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Figure: The top 30 topics of layer three of the PGBN learned on the 20newsgroups corpus.

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Figure: The top 30 topics of layer five of the PGBN learned on the 20newsgroups corpus.

Visualize the inferred deep network

- ► Visualize the whole network is challenging if the network is large.
- But we can easily visualize a tree or a subnetwork that consists of multiple trees.
- Construct a tree starting from a top-layer node: grow the tree downward by linking each leaf node of the tree to all the hidden units at the layer below that are connected to the leaf node with nonnegligible weights.



Figure: A subnetwork on "car & bike."



Figure: A subnetwork on "sports."

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Figure: A subnetwork on "gun."

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Upward-downward Gibbs sampling

Lemma (Augment-and-conquer the gamma belief network) With $p_i^{(1)} := 1 - e^{-1}$ and

$$p_j^{(t+1)} := -\ln(1-p_j^{(t)}) \Big/ \left[c_j^{(t+1)} - \ln(1-p_j^{(t)})
ight]$$

for t = 1, ..., T, one may connect the observed or latent counts $\mathbf{x}_{j}^{(t)} \in \mathbb{Z}^{K_{t-1}}$ to the product $\mathbf{\Phi}^{(t)} \mathbf{\theta}_{j}^{(t)}$ at layer t under the Poisson likelihood as

$$m{x}_{j}^{(t)} \sim \textit{Pois}\left[-m{\Phi}^{(t)}m{ heta}_{j}^{(t)}\ln\left(1-m{ heta}_{j}^{(t)}
ight)
ight]$$

Upward propagate latent counts

Corollary (Propagate the latent counts upward) With $m_{kj}^{(t)(t+1)} := x_{jk}^{(t)} := \sum_{v=1}^{K_{t-1}} x_{vjk}^{(t)}$ representing the number of times that factor $k \in \{1, \ldots, K_t\}$ of layer t appears in observation j, we can propagate the latent counts $x_{vj}^{(t)}$ of layer t upward to layer t + 1 as

$$\left\{ \left(x_{vj1}^{(t)}, \dots, x_{vjK_t}^{(t)} \right) \, \middle| \, x_{vj}^{(t)}, \phi_{V:}^{(t)}, \theta_j^{(t)} \right\} \sim Mult \left(x_{vj}^{(t)}, \frac{\phi_{v1}^{(t)} \theta_{1j}^{(t)}}{\sum_{k=1}^{K_t} \phi_{vk}^{(t)} \theta_{kj}^{(t)}}, \dots, \frac{\phi_{vK_t}^{(t)} \theta_{K_tj}^{(t)}}{\sum_{k=1}^{K_t} \phi_{vk}^{(t)} \theta_{kj}^{(t)}} \right),$$

$$(\phi_k^{(t)}|-) \sim Dir\left(\eta_1^{(t)} + x_{1\cdot k}^{(t)}, \dots, \eta_{K_{t-1}}^{(t)} + x_{K_{t-1}\cdot k}^{(t)}\right),$$

$$\left(x_{kj}^{(t+1)} \mid m_{kj}^{(t)(t+1)}, \phi_{k:}^{(t+1)}, \theta_{j}^{(t+1)}\right) \sim CRT\left(m_{kj}^{(t)(t+1)}, \phi_{k:}^{(t+1)}\theta_{j}^{(t+1)}\right)$$

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Downward sample the hidden units

Using the latent counts propagated upward and the gamma-Poisson conjugacy, we downward sample the hidden units as

$$(r_{k}|-) \sim \operatorname{Gam}\left(\gamma_{0}/K_{T} + x_{k}^{(T+1)}, \left[c_{0} - \sum_{j} \ln\left(1 - p_{j}^{(T+1)}\right)\right]^{-1}\right),$$

$$(\theta_{j}^{(T)}|-) \sim \operatorname{Gam}\left(\mathbf{r} + \mathbf{m}_{j}^{(T)(T+1)}, \left[c_{j}^{(T+1)} - \ln\left(1 - p_{j}^{(T)}\right)\right]^{-1}\right),$$

$$(\theta_{j}^{(T-1)}|-) \sim \operatorname{Gam}\left(\mathbf{\Phi}^{(T)}\theta_{j}^{(T)} + \mathbf{m}_{j}^{(T)(T+1)}, \left[c_{j}^{(T)} - \ln\left(1 - p_{j}^{(T-1)}\right)\right]^{-1}\right),$$

$$\vdots$$

$$(\boldsymbol{\theta}_{j}^{(t)} \mid -) \sim \mathsf{Gam}\left(\mathbf{\Phi}^{(t+1)} \boldsymbol{\theta}_{j}^{(t+1)} + \boldsymbol{m}_{j}^{(t)(t+1)}, \left[c_{j}^{(t+1)} - \ln\left(1 - p_{j}^{(t)}
ight)
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ight),$$

$$(m{ heta}_{j}^{(1)}|-) \sim \mathsf{Gam}\left(m{\Phi}^{(2)}m{ heta}_{j}^{(2)} + m{m}_{j}^{(1)(2)}, \left[c_{j}^{(2)} - \ln\left(1 - p_{j}^{(1)}
ight)
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Modeling overdispersion with distributed representation Assuming $\Phi^{(t)} = I$ for all $t \in 3, ..., T$, we have

$$m_{kj}^{(1)(2)} \sim \mathsf{NB}(\theta_{kj}^{(2)}, p_j^{(2)}), \dots, \theta_{kj}^{(t)} \sim \mathsf{Gam}(\theta_{kj}^{(t+1)}, 1/c_j^{(t+1)}), \dots, \theta_{kj}^{(T)} \sim \mathsf{Gam}(r_k, 1/c_j^{(T+1)}).$$

▶ In comparison to PFA with $m_{kj}^{(1)(2)} \sim NB(r_k, p_j^{(2)})$, the PGBN increases $VMR[m_{kj}^{(1)(2)} | r_k]$ by a factor of

$$1 + p_j^{(2)} \sum_{t=3}^{T+1} \left[\prod_{\ell=3}^t \left(c_j^{(\ell)} \right)^{-1} \right],$$

which is equal to

$$1 + (T-1) p_j^{(2)}$$

if we further assume $c_j^{(t)} = 1$ for all $t \ge 3$.

Therefore, by increasing the depth of the network to distribute the variance into more layers, the multilayer structure could increase its capability to model data variability.

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-Hierarchical model

- Capturing the correlations between factors

For the GBN with T = 1, given the shared weight vector \mathbf{r} , we have

$$\mathbb{E}\big[\boldsymbol{x}_{j}^{(1)} \,\big|\, \boldsymbol{\Phi}^{(1)}, \boldsymbol{r}\big] = \boldsymbol{\Phi}^{(1)} \boldsymbol{r} / c_{j}^{(2)};$$

▶ For the GBN with $T \ge 2$, given the weight vector $\theta_i^{(2)}$, we have

$$\mathbb{E}\big[\boldsymbol{x}_j^{(1)} \,\big|\, \boldsymbol{\Phi}^{(1)}, \boldsymbol{\Phi}^{(2)}, \boldsymbol{\theta}_j^{(2)}\big] = \boldsymbol{\Phi}^{(1)} \boldsymbol{\Phi}^{(2)} \boldsymbol{\theta}_j^{(2)} / c_j^{(2)}.$$

- ► Thus in the prior, the co-occurrence patterns of the columns of $\Phi^{(1)}$ are captured in a single vector \mathbf{r} when T = 1, and are captured in the columns of $\Phi^{(2)}$ when $T \ge 2$.
- ▶ Similarly, in the prior, if $T \ge t + 1$, the co-occurrence patterns of the K_t columns of the projected topics $\prod_{\ell=1}^t \Phi^{(\ell)}$ will be captured in the columns of the $K_t \times K_{t+1}$ matrix $\Phi^{(t+1)}$.



Figure: The tree rooted at node 30 of layer three on "Turkey & Armenia."

Gamma Belief Networks

-Hierarchical model

Learning the network structure with greedy layer-wise training

Inputs: observed counts $\{x_{v_i}\}_{v,i}$, upper bound of the width of the first layer $K_{1 \max}$, upper bound of the number of layers T_{max} , number of iterations $\{B_T, S_T\}_{1,T_{\text{max}}}$, and hyper-parameters. **Outputs:** A total of T_{max} jointly trained PGBNs with depths $T = 1, T = 2, ..., \text{ and } T = T_{\text{max}}$. 1: for $T = 1, 2, ..., T_{\text{max}}$ do Jointly train all the T layers of the network Set K_{T-1} , the inferred width of layer T-1, as $K_{T \max}$, the upper bound of layer T's width. 2: for $iter = 1: B_T + C_T$ do Upward-downward Gibbs sampling 3: Sample $\{z_{ji}\}_{j,i}$ using collapsed inference; Calculate $\{x_{nik}^{(1)}\}_{v,k,j}$; Sample $\{x_{ni}^{(2)}\}_{v,j}$; 4: 5: for t = 2, 3, ..., T do Sample $\{x_{v,ik}^{(t)}\}_{v,i,k}$; Sample $\{\phi_k^{(t)}\}_k$; Sample $\{x_{vi}^{(t+1)}\}_{v,j}$; 6: 7: end for Sample $p_i^{(2)}$ and Calculate $c_i^{(2)}$; Sample $\{c_i^{(t)}\}_{i,t}$ and Calculate $\{p_i^{(t)}\}_{i,t}$ for $t = 3, \ldots, T+1$ 8: for t = T, T - 1, ..., 2 do 9: Sample r if t = T; Sample $\{\boldsymbol{\theta}_i^{(t)}\}_i$; 10: end for 11: if $iter = B_T$ then 12:Prune layer T's inactive factors $\{\phi_k^{(T)}\}_{k:x^{(T)}=0}$; 13: let $K_T = \sum_k \delta(x_{i,k}^{(T)} > 0)$ and update r; 14: 15: end if end for 16: Output the posterior means (according to the last MCMC sample) of all remaining factors 17: $\{\phi_{k}^{(t)}\}_{k,t}$ as the inferred network of T layers, and $\{r_{k}\}_{k=1}^{K_{T}}$ as the gamma shape parameters of layer T's hidden units.

18: end for

Modeling binary and nonnegative real observations

We link binary observations to the latent counts at layer one as

$$b_{vj}^{(1)} = \mathbf{1} (x_{vj}^{(1)} \ge 1).$$

 For inference, we sample the latent counts at layer one from the truncated Poisson distribution as

$$(x_{vj}^{(1)} \mid -) \sim b_{vj}^{(1)} \cdot \mathsf{Pois}_{+} \left(\sum_{k=1}^{K_1} \phi_{vk}^{(1)} \theta_{kj}^{(1)} \right)$$

- ► We link nonnegative real observations to the latent counts at layer one using $y_{vi}^{(1)} \sim \text{Gam}(x_{vi}^{(1)}, 1/a_i).$
 - ► For inference, we let x⁽¹⁾_{vj} = 0 if y⁽¹⁾_{vj} = 0 and sample x⁽¹⁾_{vj} from the truncated Bessel distribution as

$$(x_{vj}^{(1)} \mid -) \sim \mathsf{Bessel}_{-1} \left(2 \sqrt{\mathsf{a}_j y_{vj}^{(1)} \sum_{k=1}^{K_1} \phi_{vk}^{(1)} \theta_{kj}^{(1)}} \right)$$

if $y_{vj}^{(1)} > 0$.

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Example results

Count data

Multivariate count data

- Train on the 20 newsgroups dataset, each document of which is summarized as a word count vector over the vocabulary.
 - We use all 11,269 training documents to infer a five layer network.
 - After removing stopwords and terms that appear less than five times, we obtain a vocabulary with $K_0 = 33,420$.
 - With $\eta^{(t)} = 0.05$ for all *t*, the inferred network widths by the PGBN are $[K_1, K_2, K_3, K_4, K_5] =$
 - [50, 50, 50, 50, 50] for $K_{1 \max} = 50$
 - [100, 99, 99, 94, 87] for $K_{1 \max} = 100$
 - [200, 161, 130, 94, 63] for $K_{1 \max} = 200$
 - [396, 109, 99, 82, 68] for $K_{1 max} = 400$
 - [528, 129, 109, 98, 91] for $K_{1 \max} = 600$
 - [608, 100, 99, 96, 89] for $K_{1 \max} = 800$

• Test on the 7,505 documents in the testing set.

Feature learning for multi-class classification



Figure: Classification accuracy (%) of the PGBNs with Algorithm 1 for 20 newsgroups multi-class classification (a) as a function of the depth T with various $K_{1 \text{ max}}$ and (b) as a function of $K_{1 \text{ max}}$ with various depths, with $\eta^{(t)} = 0.05$ for all layers.

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Prediction of heldout words



Figure: (a) per-heldout-word perplexity (the lower the better) for the NIPS12 corpus (using the 2000 most frequent terms) as a function of the upper bound of the first layer width $K_{1 \text{ max}}$ and network depth T, with 30% of the word tokens in each document used for training and $\eta^{(t)} = 0.05$ for all t. (b) for visualization, each curve in (a) is reproduced by subtracting its values from the average perplexity of the single-layer network.

• Draw $\theta^{(T)}, \theta^{(T-1)}, \dots, \theta^1$ using $\boldsymbol{\theta}_{j'}^{(\mathcal{T})} \sim \mathsf{Gam}\left(\boldsymbol{r}, \left[\boldsymbol{c}_{j'}^{(\mathcal{T}+1)}\right]^{-1}\right),$ $\boldsymbol{\theta}_{j'}^{(\mathcal{T}-1)} \sim \mathsf{Gam}\left(\boldsymbol{\Phi}^{(\mathcal{T})} \boldsymbol{\theta}_{j'}^{(\mathcal{T})}, \left[c_{j'}^{(\mathcal{T})}\right]^{-1}\right),$ $\boldsymbol{\theta}_{j'}^{(t)} \sim \mathsf{Gam}\left(\boldsymbol{\Phi}^{(t+1)} \boldsymbol{\theta}_{j'}^{(t+1)}, \left[c_{j'}^{(t+1)}\right]^{-1}
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- Calculate $E[\mathbf{x}_{j'}^{(1)}] = \mathbf{\Phi}^{(1)} \boldsymbol{\theta}_{j'}^{(1)}$
- Display the top 100 words

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Gamma Belief Networks

Example results

–Binary data

Modeling high-dimensional sparse binary vectors



Figure: Results of the BerPo-GBNs on the binarized 20newsgroups term-document count matrix. The widths of the hidden layers are automatically inferred. In a random trial with Algorithm 2, the inferred network widths $[K_1, \ldots, K_5]$ for $K_{1 \text{ max}} = 50, 100, 200, 400, 600, \text{ and } 800 \text{ are } [50, 50, 50, 50, 50], [100, 97, 95, 90, 82], [178, 145, 122, 97, 72], [184, 139, 119, 101, 75], [172, 165, 158, 138, 110], and [156, 151, 147, 134, 117], respectively.$

Example results

Nonnegative real data

Modeling high-dimensional sparse nonnegative real vectors

- Train on the 60,000 MNIST digits in the training set, each digit of which is represented as a 784 dimensional nonnegative real vector.
 - We use all 60,000 to infer a five layer network.
 - With η^(t) = 0.05 for all t, the inferred network widths by the gamma-PGBN are [K₁, K₂, K₃, K₄, K₅] =
 - [50, 50, 50, 50, 50] for $K_{1 \max} = 50$
 - [100, 100, 100, 100, 100] for $K_{1 \max} = 100$
 - [200, 200, 200, 200, 200] for $K_{1 max} = 200$
 - [400, 400, 399, 385, 321] for $K_{1 \max} = 400$
 - Test on the 10,000 MNIST digits in the test set.



Figure: Visualization of the inferred $\{\Phi^{(1)}, \dots, \Phi^{(T)}\}$ with $K_{1max} = 100$. All Φ 's are projected to the first layer. First row from left to right: $\Phi^{(1)}, \Phi^{(1)}\Phi^{(2)}, \Phi^{(1)}\Phi^{(2)}\Phi^{(3)}$

Second row from left to right: $\Phi^{(1)}\Phi^{(2)}\Phi^{(3)}\Phi^{(4)}$, $\Phi^{(1)}\Phi^{(2)}\Phi^{(3)}\Phi^{(4)}\Phi^{(5)}$.



Figure: Visualization of the inferred $\{\Phi^{(1)}, \dots, \Phi^{(T)}\}$ with $K_{1max} = 400$. All Φ 's are projected to the first layer. From (a) to (e): $\Phi^{(1)}, \Phi^{(1)}\Phi^{(2)}, \Phi^{(1)}\Phi^{(2)}\Phi^{(3)}, \Phi^{(1)}\Phi^{(2)}\Phi^{(3)}\Phi^{(4)}, \Phi^{(1)}\Phi^{(2)}\Phi^{(3)}\Phi^{(4)}\Phi^{(5)}$.





Figure: Left: layers 5 to 4;

Right: layers 4 to 3



Figure: Left: layers 3 to 2;

Right: layers 2 to 1

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Figure: Left: Classification accuracy (%) of the PRG-GBNs with various K_{1max} as a function of T_{1max} . Right: Classification accuracy (%) of the PRG-GBNs with various depths as a function of K_{1max} . $(T_{max} \in \{1, \dots, 5\})$.

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Conclusions

- The Poisson gamma belief network is proposed to extract a multilayer representation for high-dimensional count vectors.
- An upward-downward Gibbs sampler is used to jointly train all layers.
- A layer-wise training strategy is used to automatically infer the network structure.
- Extension to modeling binary and nonnegative real data.
- Understanding the data by examining the features of different layers and their relationships using the structure of the network.
- For big data problems, in practice one may rarely has a sufficient budget to allow the first-layer width to grow without bound, thus it is natural to consider a deep network that can use a multilayer deep representation to better allocate its resource and increase its representation power with limited computational power.
- Our algorithm provides a natural solution to achieve a good compromise between the width of each layer and the depth of the network.