

Nonparametric Bayesian Negative Binomial Factor Analysis

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Abstract. A common approach to analyze a covariate-sample count matrix, an element of which represents how many times a covariate appears in a sample, is to factorize it under the Poisson likelihood. We show its limitation in capturing the tendency for a covariate present in a sample to both repeat itself and excite related ones. To address this limitation, we construct negative binomial factor analysis (NBFA) to factorize the matrix under the negative binomial likelihood, and relate it to a Dirichlet-multinomial distribution based mixed-membership model. To support countably infinite factors, we propose the hierarchical gamma-negative binomial process. By exploiting newly proved connections between discrete distributions, we construct two blocked and a collapsed Gibbs sampler that all adaptively truncate their number of factors, and demonstrate that the blocked Gibbs sampler developed under a compound Poisson representation converges fast and has low computational complexity. Example results show that NBFA has a distinct mechanism in adjusting its number of inferred factors according to the sample lengths, and provides clear advantages in parsimonious representation, predictive power, and computational complexity over previously proposed discrete latent variable models, which either completely ignore burstiness, or model only the burstiness of the covariates but not that of the factors.

Keywords: Burstiness, count matrix factorization, hierarchical gamma-negative binomial process, parsimonious representation, self- and cross-excitation

1 Introduction

The need to analyze a covariate-sample count matrix, each of whose elements counts the number of time that a covariate appears in a sample, arises in many different settings, such as text analysis, next-generation sequencing, medical records mining, and consumer behavior studies. The mixed-membership model, widely used for text analysis (Blei et al. 2003) and population genetics (Pritchard et al. 2000), treats each sample as a bag of indices (words), and associates each index with both a covariate that is observed and a subpopulation that is latent. It makes the assumption that there are K latent subpopulations, each of which is characterized by how frequent the covariates are relative to each other within it. Given the total number of indices for a sample, it assigns each index independently to one of the K subpopulations, with a probability proportional to the product of the corresponding covariate's relative frequency in that subpopulation and that subpopulation's relative frequency in the sample. A mixed-membership model constructed in this manner, as shown in Zhou et al. (2012) and Zhou and Carin (2015),

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can also be connected to Poisson factor analysis (PFA) that factorizes the covariate-sample count matrix, under the Poisson likelihood, into the product of a nonnegative covariate-subpopulation factor loading matrix and a nonnegative subpopulation-sample factor score matrix. Each column of the factor loading matrix encodes the relative frequencies of the covariates in a subpopulation, while that of the factor score matrix encodes the weights of the subpopulations in a sample.

Despite the popularity of both approaches in analyzing the covariate-sample count matrix, they both make restrictive assumptions. Given the relative frequencies of the covariates in subpopulations and the relative frequencies of the subpopulations in samples, the mixed-membership model independently assigns each index to both a covariate and a subpopulation, and hence may not sufficiently capture the tendency for an index to excite the other ones in the same sample to take the same or related covariates. Whereas for PFA, given the factor loading and score matrices, it assumes that the variance and mean are the same for each covariate-sample count, and hence is likely to underestimate the variability of overdispersed counts.

In practice, however, highly overdispersed covariate-sample counts are frequently observed due to self- and cross-excitation of covariate frequencies, that is to say, some covariates are particularly intense and also make other related covariates intense. For example, the tendency for a word present in a document to appear repeatedly is a fundamental phenomenon in natural language that is commonly referred to as word burstiness (Church and Gale 1995; Madsen et al. 2005; Doyle and Elkan 2009). If a word is bursty in a document, it is also common for it to excite (stimulate) related words to exhibit burstiness. Without capturing the self- and cross-excitation (stimulation) of covariate frequencies or better modeling the overdispersed covariate-sample counts, the ultimate potential of the mixed-membership model and PFA will be limited no matter how the priors on latent parameters are adjusted. In addition, it could be a waste of computation if the model tries to increase the model capacity to better capture overdispersions that could be simply explained with self- and cross-excitations.

To remove these restrictions, we introduce negative binomial factor analysis (NBFA) to factorize the covariate-sample count matrix, in which we replace the Poisson distributions on which PFA is built, with the negative binomial (NB) distributions. As PFA is closely related to the canonical mixed-membership model built on the multinomial distribution, we show that NBFA is closely related to a Dirichlet-multinomial mixed-membership (DMMM) model that uses the Dirichlet-categorical (Dirichlet-multinomial) rather than categorical (multinomial) distributions to assign an index to both a covariate and a factor (subpopulation). From the viewpoint of count modeling, NBFA improves PFA by better modeling overdispersed counts, while from that of mixed-membership modeling, it improves the canonical mixed-membership model by capturing the burstiness at both the covariate and factor levels (*i.e.*, for topic modeling, it exhibits a rich-get-richer phenomenon at both the word and topic levels). In addition, we will show NBFA could significantly reduce the computation spent on large covariate-sample counts.

Note that with a different likelihood for counts and a different mechanism to generate both the covariate and factor indices, NBFA and the related DMMM model pro-

posed in the paper complement, rather than compete with, PFA (Zhou et al. 2012; Zhou and Carin 2015). First, NBFA provides more significant advantages in modeling longer samples, where there is more need to capture both self- and cross-excitation of covariate frequencies. Second, various extensions built on PFA or the multinomial mixed-membership model, such as capturing the correlations between factors (Blei and Lafferty 2005; Paisley et al. 2012) and learning multilayer deep representations (Ranganath et al. 2015; Gan et al. 2015; Zhou et al. 2016a), could also be applied to extend NBFA. In this paper, we will focus on constructing a nonparametric Bayesian NBFA with a potentially infinite number of factors, and leave a wide variety of potential extensions under this new framework to future research.

To avoid the need of selecting the number of factors K , for PFA and the closely related multinomial mixed-membership model, a number of nonparametric Bayesian priors can be employed to support a potentially infinite number of latent factors, such as the hierarchical Dirichlet process (Teh et al. 2006) and beta-negative binomial process (Zhou et al. 2012; Broderick et al. 2015; Zhou and Carin 2015). To support countably infinite factors for NBFA, generalizing the gamma-negative binomial process (GNBP) (Zhou and Carin 2015; Zhou et al. 2016b), we introduce a new nonparametric Bayesian prior: the hierarchical gamma-negative binomial process (hGNBP), where each of the J samples is assigned with a sample-specific GNBP and a globally shared gamma process is mixed with all the J GNBP. We derive both blocked and collapsed Gibbs sampling for the hGNBP-NBFA, with the number of factors automatically inferred.

The remainder of the paper is organized as follows. In Section 2, we review PFA and the multinomial mixed-membership model. In Section 3, we introduce NBFA and its representation as a DMMM model, and compare them with related models. In Section 4, we propose nonparametric-Bayesian NBFA. In Section 5, we derive both blocked and collapsed Gibbs sampling algorithms. In Section 6, we first make comparisons between different sampling strategies and then compare the performance of various algorithms on real data. We conclude the paper in Section 7. The proofs and Gibbs sampling update equations are provided in the Supplementary Material.

2 Poisson factor analysis and mixed-membership model

2.1 Poisson factor analysis

Let \mathbf{N} be a $V \times J$ covariate-sample count matrix for V covariates among J samples, where n_{vj} is the (v, j) element of \mathbf{N} and gives the number of times that sample j has covariate v . PFA factorizes \mathbf{N} under the Poisson likelihood as

$$\mathbf{N} \sim \text{Pois}(\Phi\Theta), \quad (1)$$

where ‘‘Pois’’ is the abbreviation for ‘‘Poisson,’’ $\Phi = (\phi_1, \dots, \phi_K) \in \mathbb{R}_+^{V \times K}$ represents the factor loading matrix, $\Theta = (\theta_1, \dots, \theta_J) \in \mathbb{R}_+^{K \times J}$ represents the factor score matrix, and $\mathbb{R}_+ = \{x : x \geq 0\}$, with $\phi_k = (\phi_{1k}, \dots, \phi_{V_k})^T$ encoding the weights of the V covariates in factor k and $\theta_j = (\theta_{1j}, \dots, \theta_{Kj})^T$ encoding the popularity of the K factors

in sample j . PFA in (1) has an augmented representation as

$$n_{vj} = \sum_{k=1}^K n_{vjk}, \quad n_{vjk} \sim \text{Pois}(\phi_{vk}\theta_{kj}). \quad (2)$$

As in Zhou et al. (2012), it can also be equivalently constructed by first generating n_{vj} and then assigning them to the latent factors using the multinomial distributions as

$$(n_{vj1}, \dots, n_{vjK}) | n_{vj} \sim \text{Mult}\left(n_{vj}, \frac{\phi_{v1}\theta_{1j}}{\sum_{k=1}^K \phi_{vk}\theta_{kj}}, \dots, \frac{\phi_{vK}\theta_{Kj}}{\sum_{k=1}^K \phi_{vk}\theta_{kj}}\right), \quad n_{vj} \sim \text{Pois}\left(\sum_{k=1}^K \phi_{vk}\theta_{kj}\right). \quad (3)$$

2.2 Multinomial mixed-membership model

This alternative representation suggests a potential link of PFA to a standard mixed-membership model for text analysis such as probabilistic latent semantic analysis (PLSA) (Hofmann 1999) and latent Dirichlet allocation (LDA) (Blei et al. 2003). Given the factors ϕ_k and factor proportions $\theta_j/\theta_{\cdot j}$, where $\sum_{v=1}^V \phi_{vk} = 1$ and $\theta_{\cdot j} := \sum_{k=1}^K \theta_{kj}$, a standard procedure is to associate $x_{ji} \in \{1, \dots, V\}$, the i th index (word) of sample j , with factor (topic) $z_{ji} \in \{1, \dots, K\}$, and generate a bag of indices $\{x_{j1}, \dots, x_{jn_j}\}$ as

$$x_{ji} \sim \text{Cat}(\phi_{z_{ji}}), \quad z_{ji} \sim \text{Cat}(\theta_j/\theta_{\cdot j}), \quad (4)$$

where $n_j = \sum_{v=1}^V n_{vj}$ and $n_{vj} = \sum_{i=1}^{n_j} \delta(x_{ji} = v)$. We refer to (4) as the multinomial mixed-membership model. LDA completes the multinomial mixed-membership model by imposing the Dirichlet priors on both $\{\phi_k\}_k$ and $\{\theta_j/\theta_{\cdot j}\}_j$ (Blei et al. 2003).

If in addition to the multinomial mixed-membership model described in (4), one further generates the sample lengths as

$$n_j \sim \text{Pois}(\theta_{\cdot j}), \quad (5)$$

then the joint likelihood of $\mathbf{x}_j := (x_{j1}, \dots, x_{jn_j})$, $\mathbf{z}_j := (z_{j1}, \dots, z_{jn_j})$, and n_j given Φ and θ_j can be expressed as

$$P(\mathbf{x}_j, \mathbf{z}_j, n_j | \Phi, \theta_j) = \frac{\prod_{v=1}^V \prod_{k=1}^K n_{vjk}!}{n_j!} \prod_{v=1}^V \prod_{k=1}^K \text{Pois}(n_{vjk}; \phi_{vk}\theta_{kj}),$$

whose product with the combinatorial coefficient $n_j!/(\prod_{v=1}^V \prod_{k=1}^K n_{vjk}!)$ becomes the same as the likelihood $P(\{n_{vj}, n_{vj1}, \dots, n_{vjK}\}_v | \Phi, \theta_j)$ of (2).

From the viewpoint of PFA, shown in (2), and its alternative representation constituted by (4) and (5), a wide variety of discrete latent variable models, such as nonnegative matrix factorization (NMF) (Lee and Seung 2001), PLSA, LDA, the gamma-Poisson model of Canny (2004), and the discrete component analysis of Buntine and Jakulin (2006), all have the same mechanism to model the covariate counts that they generate both the covariate and factor indices using the categorical distributions shown in (4); they mainly differ from each other on how the priors on ϕ_k and θ_j (or $\theta_j/\theta_{\cdot j}$) are constructed (Zhou et al. 2012; Zhou and Carin 2015).

3 Negative binomial factor analysis and Dirichlet-multinomial mixed-membership model

3.1 Negative binomial factor analysis

To better model overdispersed counts, instead of following PFA to factorize the covariate-sample count matrix under the Poisson likelihood, we propose negative binomial (NB) factor analysis (NBFA) to factorize it under the NB likelihood as

$$\mathbf{n}_j \sim \text{NB}(\Phi \boldsymbol{\theta}_j, p_j),$$

where $n \sim \text{NB}(r, p)$ denote the NB distribution with PMF $f_N(n | r, p) = \frac{\Gamma(n+r)}{n! \Gamma(r)} p^n (1-p)^r$, where $n \in \{0, 1, \dots\}$. NBFA has an augmented representation as

$$n_{vj} = \sum_{k=1}^K n_{vjk}, \quad n_{vjk} \sim \text{NB}(\phi_{vk} \theta_{kj}, p_j). \quad (6)$$

Similar to how the Poisson distribution is related to the multinomial distribution (e.g., Dunson and Herring (2005) and Lemma 4.1 of Zhou et al. (2012)), we reveal how the NB distribution is related to the Dirichlet-multinomial distribution using Theorem 1 shown below, whose proof is provided in Appendix A. As in Mosimann (1962), marginalizing out $\boldsymbol{\theta}$ from $\mathbf{z} \sim \prod_{i=1}^n \text{Cat}(z_i; \boldsymbol{\theta})$, $\boldsymbol{\theta} \sim \text{Dir}(r_1, \dots, r_K)$ leads to a Dirichlet-categorical (DirCat) distribution with PMF

$$P(\mathbf{z} | r_1, \dots, r_K) = \frac{\Gamma(r_{\cdot})}{\Gamma(n + r_{\cdot})} \prod_{k=1}^K \frac{\Gamma(n_k + r_k)}{\Gamma(r_k)}, \quad (7)$$

where $n_k = \sum_{i=1}^n \delta(z_i = k)$, and a Dirichlet-multinomial (DirMult) distribution with PMF $P[(n_1, \dots, n_K) | r_1, \dots, r_K] = \frac{n!}{\prod_{k=1}^K n_k!} P(\mathbf{z} | r_1, \dots, r_K)$.

Theorem 1 (The negative binomial and Dirichlet-multinomial distributions). *Let $\mathbf{x} = (x, x_1, \dots, x_K)$ be random variables generated as*

$$x = \sum_{k=1}^K x_k, \quad x_k \sim \text{NB}(r_k, p).$$

Set $r_{\cdot} = \sum_{k=1}^K r_k$ and let $\mathbf{y} = (y, y_1, \dots, y_K)$ be random variables generated as

$$(y_1, \dots, y_K) \sim \text{DirMult}(y, r_1, \dots, r_K), \quad y \sim \text{NB}(r_{\cdot}, p).$$

Then the distribution of \mathbf{x} is the same as that of \mathbf{y} .

Using Theorem 1, $(n_{vj}, n_{vj1}, \dots, n_{vjK})$ in (6) can be equivalently generated as

$$(n_{vj1}, \dots, n_{vjK}) | n_{vj} \sim \text{DirMult}(n_{vj}, \phi_{v1} \theta_{1j}, \dots, \phi_{vK} \theta_{Kj}), \quad n_{vj} \sim \text{NB}\left(\sum_{k=1}^K \phi_{vk} \theta_{kj}, p_j\right). \quad (8)$$

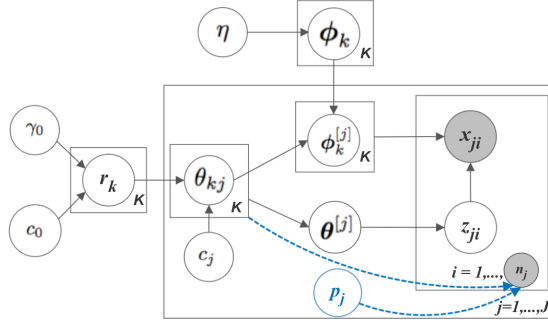


Figure 1: Graphical representations of the Dirichlet-multinomial mixed-membership model (without p_j and the dashed lines) and negative binomial factor analysis (with p_j and the dashed lines).

Clearly, how the factorization under the NB likelihood is related to the Dirichlet-multinomial distribution, as in (6) and (8), mimics how the factorization under the Poisson likelihood is related to the multinomial distribution, as in (2) and (3).

3.2 The Dirichlet-multinomial mixed-membership model

Similar to how we relate PFA in (2) to the multinomial topic model in (4), as in Section 2.1, we may relate NBFA in (6) to a mixed-membership model constructed by replacing the categorical distributions in (4) with the Dirichlet-categorical distributions as

$$\begin{aligned} x_{ji} &\sim \text{Cat}(\phi_{z_{ji}}^{[j]}), \quad z_{ji} \sim \text{Cat}(\theta^{[j]}), \\ \phi_k^{[j]} &\sim \text{Dir}(\phi_k \theta_{kj}), \quad \theta^{[j]} \sim \text{Dir}(\theta_j), \end{aligned} \quad (9)$$

where $\{\phi_k^{[j]}\}_k$ and $\theta^{[j]}$ represent the factors and factor scores specific for sample j , respectively. A graphical representation of the model, including the settings of the hyper-priors to be discussed later, is shown in Figure 1. Introducing $\phi_k^{[j]}$ into the hierarchical model allows the same set of factors $\{\phi_k\}_k$ to be manifested differently in different samples, whereas introducing $\theta^{[j]}$ allows each sample to have two different representations: the factor scores $\theta^{[j]}$ under the sample-specific factors $\{\phi_k^{[j]}\}_k$, and the factor scores θ_j under the shared factors $\{\phi_k\}_k$. In addition, under this construction, the variance-to-mean ratio of $\phi_{vk}^{[j]}$ given ϕ_k and θ_{kj} becomes $(1 - \phi_{vk})/(\theta_{kj} + 1)$, which monotonically decreases as the corresponding factor score θ_{kj} increases, allowing the variability of $\phi_k^{[j]}$ in the prior to be controlled by the popularity of ϕ_k in the corresponding sample. Moreover, this construction helps simplify the model likelihood and allows the model to be closely related to NBFA, as discussed below.

Explicitly drawing $\{\phi_k^{[j]}\}_k$ for all samples would be computationally prohibitive, especially if the number of samples is large. Fortunately, this operation is totally unnecessary. By marginalizing out $\phi_k^{[j]}$ and $\theta^{[j]}$ in (9), we have

$$\{x_{ji}\}_{i:z_{ji}=k} \sim \text{DirCat}(n_{\cdot jk}, \phi_{1k}\theta_{kj}, \dots, \phi_{Vk}\theta_{kj}), \quad \mathbf{z}_j \sim \text{DirCat}(n_j, \boldsymbol{\theta}_j), \quad (10)$$

where $\mathbf{z}_j := (z_{j1}, \dots, z_{jn_j})$, $n_{vjk} := \sum_{i=1}^{n_j} \delta(x_{ji} = v, z_{ji} = k)$, and $n_{\cdot jk} := \sum_{v=1}^V n_{vjk}$. Thus the joint likelihood of $\mathbf{x}_j := (x_{j1}, \dots, x_{jn_j})$ and \mathbf{z}_j given $\boldsymbol{\Phi}$, $\boldsymbol{\theta}_j$, and n_j can be expressed as

$$P(\mathbf{x}_j, \mathbf{z}_j | \boldsymbol{\Phi}, \boldsymbol{\theta}_j, n_j) = \frac{\Gamma(\boldsymbol{\theta}_j)}{\Gamma(n_j + \boldsymbol{\theta}_j)} \prod_{v=1}^V \prod_{k=1}^K \frac{\Gamma(n_{vjk} + \phi_{vk}\theta_{kj})}{\Gamma(\phi_{vk}\theta_{kj})}. \quad (11)$$

We call the model shown in (9) or (10) as the Dirichlet-multinomial mixed-membership (DMMM) model, whose likelihood given the factors and factor scores is shown in (11).

We introduce the following proposition, with proof provided in Appendix A, to show that one can recover NBFA from the DMMM model by randomizing its sample lengths with the NB distributions, and can reduce NBFA to the DMMM model by conditioning on these lengths. Thus how NBFA and the DMMM are related to each other mimics how PFA and the multinomial mixed-membership model are related to each other.

Proposition 2 (Dirichlet-multinomial mixed-membership (DMMM) modeling and negative binomial factor analysis). *For the DMMM model that generates the covariate and factor indices using (9) or (10), if the sample lengths are randomized as*

$$n_j \sim \text{NB}(\boldsymbol{\theta}_j, p_j), \quad (12)$$

then the joint likelihood of \mathbf{x}_j , \mathbf{z}_j , and n_j given $\boldsymbol{\Phi}$, $\boldsymbol{\theta}_j$, and p_j , multiplied by the combinatorial coefficient $n_j! / (\prod_{v=1}^V \prod_{k=1}^K n_{vjk}!)$, is equal to the likelihood of negative binomial factor analysis (NBFA) described in (6) or (8), expressed as

$$P(\{n_{vj}, n_{vj1}, \dots, n_{vjK}\}_{v=1, V} | \boldsymbol{\Phi}, \boldsymbol{\theta}_j, p_j) = \prod_{v=1}^V \prod_{k=1}^K \text{NB}(n_{vj}; \phi_{vk}\theta_{kj}, p_j). \quad (13)$$

The DMMM model could model not only the burstiness of the covariates, but also that of the factors via the Dirichlet-categorical distributions, as further explained below when discussing related models. As far as the conditional posteriors of ϕ_k and $\boldsymbol{\theta}_j$ are concerned, the DMMM model with the lengths of its samples randomized via the NB distributions, as shown in (10) and (12), is equivalent to NBFA, as shown in (6). The representational differences, however, lead to different inference strategies, which will be discussed in detail along with their nonparametric Bayesian generalizations.

3.3 Comparisons with related models

Preceding the Dirichlet-multinomial mixed-membership (DMMM) model proposed in this paper, to account for covariate burstiness, Doyle and Elkan (2009) proposed Dirichlet compound multinomial LDA (DCMLDA) that can be expressed as

$$x_{ji} \sim \text{Cat}(\phi_{z_{ji}}^{[j]}), \quad z_{ji} \sim \text{Cat}(\boldsymbol{\theta}_j), \quad \phi_k^{[j]} \sim \text{Dir}(\phi_k r_k), \quad (14)$$

where the Dirichlet prior is further imposed on $\boldsymbol{\theta}_j$. Note that the sample-specific factor scores $\{\boldsymbol{\theta}_j\}_j$ are represented under the sample-specific factors $\{\phi_k^{[j]}\}_k$ in DCMLDA, as shown in (14), whereas they are represented under the same set of factors $\{\phi_k\}_k$ in the DMMM model, as shown in (10).

Comparing (9) with (14), it is clear that removing $\boldsymbol{\theta}^{[j]}$ from (9) reduces the DMMM model to DCMLDA in (14). Moreover, if we further let

$$\boldsymbol{\theta}_j \sim \text{Dir}(\mathbf{r}), \quad n_j \sim \text{NB}(r, p_j), \quad (15)$$

then the joint likelihood of \mathbf{x}_j , \mathbf{z}_j , and n_j given Φ , \mathbf{r} , and p_j can be expressed as

$$P(\mathbf{x}_j, \mathbf{z}_j, n_j \mid \Phi, \mathbf{r}, p_j) = \frac{1}{n_j!} \prod_{v=1}^V \prod_{k=1}^K \frac{\Gamma(n_{vjk} + \phi_{vk} r_k)}{\Gamma(\phi_{vk} r_k)} p_j^{n_{vjk}} (1 - p_j)^{\phi_{vk} r_k}, \quad (16)$$

which multiplied by the combinatorial coefficient $n_j! / (\prod_{v=1}^V \prod_{k=1}^K n_{vjk}!)$ is equal to the likelihood of $\{n_{vj}, n_{vj1}, \dots, n_{vjK}\}_{v=1, V}$ given Φ , \mathbf{r} , and p_j in

$$n_{vj} = \sum_{k=1}^K n_{vjk}, \quad n_{vjk} \sim \text{NB}(\phi_{vk} r_k, p_j). \quad (17)$$

Thus, as far as the conditional posteriors of $\{\phi_k\}_k$ and $\{r_k\}_k$ are concerned, DCMLDA constituted by (14)-(15) is equivalent to a special case of NBFA shown in (17), which is the augmented representation of $\mathbf{n}_j \sim \text{NB}(\Phi \mathbf{r}, p_j)$ that restricts all samples to have the same factor scores $\{r_k\}_k$ under the same set of shared factors $\{\phi_k\}_k$.

Given the factors $\{\phi_k\}_k$ and factor scores $\boldsymbol{\theta}_j$, for the multinomial mixed-membership model in (4), both the covariate and factor indices are independently drawn from the categorical distributions; for DCMLDA in (14), the factor indices but not the covariate indices are independently drawn from the categorical distributions; whereas for the DMMM model in (9), neither the factor indices nor covariate indices are independently drawn from the categorical distributions. Denoting y^{-ji} as the variable y obtained by excluding the contribution of the i th word in sample j , we compare in Table 1 these three different models on their predictive distributions of x_{ji} and z_{ji} .

In comparison to the multinomial mixed-membership model, DCMLDA allows the number of times that a covariate appears in a sample to exhibit the ‘‘rich get richer’’ (*i.e.*, self-excitation) behavior, leading to a better modeling of covariate burstiness, and the DMMM model further models the burstiness of the factor indices and hence encourages not only self-excitation, but also cross-excitation of covariate frequencies. It is clear from Table 1 that DCMLDA models covariate burstiness but not factor burstiness, and the corresponding NBFA restricts all samples to have the same factor scores under the shared factors $\{\phi_k\}_k$. Thus we expect the DMMM model to clearly outperform DCMLDA, as will be confirmed by our experimental results.

Note that Zhou et al. (2016a) have recently extended the single-layer PFA into a multilayer one. For example, a two-layer PFA would further factorize the factor scores

Table 1: Comparisons of the predictive distributions for the multinomial mixed-membership model in (4), Dirichlet compound multinomial LDA (DCMLDA) in (14), and Dirichlet-multinomial mixed-membership (DMMM) model in (9).

Model	Predictive distribution for x_{ji}	Predictive distribution for z_{ji}
Multinomial mixed-membership	$P(x_{ji} = v \Phi, \theta_j) = \phi_{vz_{ji}}$	$P(z_{ji} = k \theta_j) = \theta_{kj}/\theta_{\cdot j}$
Dirichlet compound multinomial LDA	$P(x_{ji} = v \mathbf{x}_j^{-ji}, z_{ji}, \Phi, \mathbf{r}) = \frac{n_{vjz_{ji}}^{-ji} + \phi_{vjz_{ji}} r_{z_{ji}}}{n_{\cdot jz_{ji}}^{-ji} + r_{z_{ji}}}$	$P(z_{ji} = k \theta_j) = \theta_{kj}/\theta_{\cdot j}$
Dirichlet-multinomial mixed-membership	$P(x_{ji} = v \mathbf{x}_j^{-ji}, z_{ji}, \Phi, \theta_j) = \frac{n_{vjz_{ji}}^{-ji} + \phi_{vjz_{ji}} \theta_{z_{ji}j}}{n_{\cdot jz_{ji}}^{-ji} + \theta_{z_{ji}j}}$	$P(z_{ji} = k \mathbf{z}_j^{-i}, n_j, \theta_j) = \frac{n_{\cdot jk}^{-ji} + \theta_{kj}}{n_j - 1 + \theta_{\cdot j}}$

θ_j in $\mathbf{x}_j \sim \text{Pois}(\Phi\theta_j)$ under the gamma likelihood as $\theta_j \sim \text{Gamma}[\tilde{\Phi}\tilde{\theta}_j, p_j/(1-p_j)]$, which is designed to capture the co-occurrence patterns of the first-layer factors ϕ_k . With θ_{jk} marginalized out from $n_{\cdot jk} \sim \text{Pois}(\theta_{jk})$, we have $n_{\cdot jk} \sim \text{NB}(\sum_{\tilde{k}} \tilde{\phi}_{k\tilde{k}} \tilde{\theta}_{j\tilde{k}}, p_j)$, which can be considered as a NBFA model for the latent factor-sample counts. Thus using our previous analysis on NBFA, this multilayer construction models both the self- and cross-excitations of the first-layer factors and helps capture their bustiness, which could help better explain why adding an additional layer to PFA could often lead to clearly improved modeling performance, as shown in Zhou et al. (2016a). However, due to the choice of the Poisson likelihood at the first layer, a multilayer PFA does not directly capture the bustiness of the covariates. On the other hand, the single-layer NBFA models the self-excitation but not cross-excitation of factors. Therefore, extending the single-layer NBFA into a multi-layer one by exploiting the deep structure of Zhou et al. (2016a) may combine the advantages of both by not only capturing the covariate bustiness, but also better capturing the factor bustiness. That extension is outside of the scope of the paper and we leave it for future study.

4 Hierarchical gamma-negative binomial process negative binomial factor analysis

Let $G \sim \Gamma\text{P}(G_0, 1/c_0)$ be a gamma process (Ferguson 1973) defined on the product space $\mathbb{R}_+ \times \Omega$, where $\mathbb{R}_+ = \{x : x > 0\}$, with two parameters: a finite and continuous base measure G_0 over a complete separable metric space Ω , and a scale $1/c_0$, such that $G(A) \sim \text{Gamma}(G_0(A), 1/c_0)$ for each $A \subset \Omega$. The Lévy measure of the gamma process can be expressed as $\nu(drd\phi) = r^{-1}e^{-c_0r}drG_0(d\phi)$. A draw from $G \sim \Gamma\text{P}(G_0, 1/c_0)$ can be represented as the countably infinite sum $G = \sum_{k=1}^{\infty} r_k \delta_{\phi_k}$, $\phi_k \sim g_0$, where $\gamma_0 = G_0(\Omega)$ as the mass parameter and $g_0(d\phi) = G_0(d\phi)/\gamma_0$ is the base distribution.

To support countably infinite factors for the DMMM model, we consider a hierarchical gamma-negative binomial process (hGNBP) as

$$X_j \sim \text{NBP}(\Theta_j, p_j), \Theta_j \sim \text{FP}(G, 1/c_j), G \sim \text{FP}(G_0, 1/c_0),$$

where $X \sim \text{NBP}(\Theta, p)$ is a NB process defined such that $X(A_i) \sim \text{NB}(\Theta(A_i), p)$ are independent NB random variables for disjoint partitions A_i of Ω . Given a gamma process random draw $G = \sum_{k=1}^{\infty} r_k \delta_{\phi_k}$, we have

$$\Theta_j = \sum_{k=1}^{\infty} \theta_{kj} \delta_{\phi_k}, \theta_{kj} \sim \text{Gamma}(r_k, 1/c_j),$$

where $\theta_{kj} := \Theta_j(\phi_k)$ measures the weight of factor k in sample j , and

$$X_j = \sum_{k=1}^{\infty} n_{jk} \delta_{\phi_k}, n_{jk} \sim \text{NB}(\theta_{kj}, p_j),$$

where $n_j = X_j(\Omega)$ is the length of sample j and $n_{jk} := X_j(\phi_k) = \sum_{i=1}^{n_j} \delta(z_{ji} = k)$ represents the number of times that factor k appears in sample j .

We provide posterior analysis for the proposed hGNBP in Appendix B, where we utilize several additional discrete distributions, including the Chinese restaurant table (CRT), logarithmic, and sum-logarithmic (SumLog) distributions, that will also be used in the following discussion.

4.1 Hierarchical model

We express the hGNBP-DMMM model as

$$\begin{aligned} x_{ji} &\sim \text{Cat}(\phi_{z_{ji}}^{[j]}), z_{ji} \sim \text{Cat}(\theta^{[j]}), \\ \phi_k^{[j]} &\sim \text{Dir}(\phi_k \theta_{kj}^{[j]}), \theta^{[j]} \sim \text{Dir}(\theta_j), \\ \theta_{kj} &\sim \text{Gamma}(r_k, 1/c_j), c_j \sim \text{Gamma}(e_0, 1/f_0), \\ n_j &\sim \text{NB}(\theta_j, p_j), p_j \sim \text{Beta}(a_0, b_0), G \sim \text{FP}(G_0, 1/c_0), \end{aligned} \quad (18)$$

where the atoms of the gamma process are drawn from a Dirichlet base distribution $\phi_k \sim \text{Dir}(\eta, \dots, \eta)$. We further let $\gamma_0 \sim \text{Gamma}(a_0, 1/b_0)$ and $c_0 \sim \text{Gamma}(e_0, 1/f_0)$. With Proposition 2, the above model can also be represented as a hGNBP-NBFA as

$$\begin{aligned} n_{vj} &= \sum_{k=1}^{\infty} n_{vjk}, n_{vjk} \sim \text{NB}(\phi_{vk} \theta_{kj}, p_j), \\ \theta_{kj} &\sim \text{Gamma}(r_k, 1/c_j), c_j \sim \text{Gamma}(e_0, 1/f_0), \\ p_j &\sim \text{Beta}(a_0, b_0), G \sim \text{FP}(G_0, 1/c_0). \end{aligned} \quad (19)$$

The DMMM model in (18) and NBFA in (19) have the same conditional posteriors for both the factors $\{\phi_k\}_k$ and factor scores $\{\theta_j\}_j$, but lead to different inference strategies. To infer $\{\phi_k\}_k$ and $\{\theta_j\}_j$, we first develop both blocked and collapsed Gibbs sampling with (18), and then develop blocked Gibbs sampling with (19), as described below.

5 Inference via Gibbs sampling

We present in this section three different Gibbs sampling algorithms, as summarized in Algorithm 1 in the Appendix.

5.1 Blocked Gibbs sampling

As it is impossible to draw all the countably infinite atoms of a gamma process draw, expressed as $G = \sum_{k=1}^{\infty} r_k \delta_{\phi_k}$, for the convenience of implementation, it is common to consider truncating the total number of atoms to be K by choosing a discrete base measure as $G_0 = \sum_{k=1}^K \frac{\gamma_0}{K} \delta_{\phi_k}$, under which we have $r_k \sim \text{Gamma}(\gamma_0/K, 1/c_0)$ for $k \in \{1, \dots, K\}$ (Zhou and Carin 2015). The finite truncation strategy is also commonly used for Dirichlet process mixture models (Ishwaran and James 2001; Fox et al. 2011). Although fixing K often works well in practice, it may lead to a considerable waste of computation if K is set to be too large. For nonparametric Bayesian mixture models based on the Dirichlet process (Ferguson 1973; Escobar and West 1995) or other more general normalized random measures with independent increments (NRMIs) (Regazzini et al. 2003; Lijoi et al. 2007), one may consider slice sampling to adaptively truncate the number of atoms used in each Markov chain Monte Carlo (MCMC) iteration (Walker 2007; Papaspiliopoulos and Roberts 2008). Unlike NRMIs whose atoms' weights have to sum to one and hence are negatively correlated, the weights of the atoms of completely random measures are independent from each other. Exploiting this property, for our models built on completely random measures, we construct a sampling procedure that adaptively truncates the total number of atoms in each iteration.

Note that the conditional posterior of G shown in (B.2) consists of two independent gamma processes: $\mathcal{D} \sim \text{GP}(\sum_j \tilde{L}_j, [c_0 - \sum_j \ln(1 - \tilde{p}_j)]^{-1})$ and $G_{\star} \sim \text{GP}(G_0, [c_0 - \sum_j \ln(1 - \tilde{p}_j)]^{-1})$. To approximately represent a draw from G_{\star} that consists of countably infinite atoms, at the end of each MCMC iteration, we relabel the indices of the atoms with nonzero counts from 1 to $K^+ := \sum_{k=1}^{\infty} \delta(\sum_j X_j(\phi_k) > 0)$; draw K_{\star} new atoms as

$$\tilde{G}_{\star} = \sum_{k=K^++1}^{K^++K_{\star}} r_k \delta_{\phi_k}, \quad r_k \sim \text{Gamma}\left(\frac{\gamma_0}{K_{\star}}, \frac{1}{c_0 - \sum_j \ln(1 - \tilde{p}_j)}\right), \quad \phi_k \sim \text{Dir}(\eta, \dots, \eta);$$

and set $K := K^+ + K_{\star}$ as the total number of atoms to be used for the next iteration.

For the hGNBP DMMM model, we present the update equations for z_{ji} and ℓ_{vjk} below and those for all the other parameters in Appendix C.1.

Sample z_{ji} . Using the likelihood in (11), we have

$$P(z_{ji} = k | x_{ji}, \mathbf{z}_j^{-i}, \Phi, \theta_j) \propto n_{x_{ji}jk}^{-ji} + \phi_{x_{ji}k} \theta_{kj}, \quad k \in \{1, \dots, K\}. \quad (20)$$

Sample ℓ_{vjk} . Since $n_{vjk} \sim \text{NB}(\phi_{vk} \theta_{kj}, p_j)$ in the prior, as shown in Proposition 2, we can draw a corresponding latent count ℓ_{vjk} for each n_{vjk} as

$$(\ell_{vjk} | -) \sim \text{CRT}(n_{vjk}, \phi_{vk} \theta_{kj}), \quad (21)$$

where $\ell_{vjk} = 0$ almost surely if $n_{vjk} = 0$.

5.2 Collapsed Gibbs sampling

Let us denote $\mathbf{b} \sim \text{CRP}(n, r)$ as an exchangeable random partition of the set $\{1, \dots, n\}$, generated by assigning n customers (samples) to ℓ random number of tables (exclusive and nonempty subsets) using a Chinese restaurant process (CRP) (Aldous 1983) with concentration parameter r . The exchangeable partition probability function of \mathbf{b} under the CRP, also known as the Ewens sampling formula (Ewens 1972; Antoniak 1974), can be expressed as $P(\mathbf{b} | n, r) = \frac{\Gamma(r)\ell^\ell}{\Gamma(n+r)} \prod_{t=1}^{\ell} \Gamma(n_t)$, where $n_t = \sum_{i=1}^n \delta(b_i = t)$ is the size of the t th subset and ℓ is the number of subsets (Pitman 2006).

One common strategy to improve convergence and mixing for multinomial mixed-membership models is to collapse the factors $\{\phi_k\}_k$ and factor scores $\{\theta_j\}_j$ in the sampler (Griffiths and Steyvers 2004; Newman et al. 2009). To apply this strategy to the DMMM model, we first need to transform the likelihood in (16) to make it amenable to marginalization. Using an analogy similar to that for the Chinese restaurant franchise of Teh et al. (2006), if we consider z_{ji} as the index of the “dish” that the i th “customer” in the j th “restaurant” takes, then, to make the likelihood in (16) become fully factorized, we may introduce b_{ji} as the index of the table at which this customer is seated. The following proposition, whose proof is provided in Appendix A, reveals how the CRP can be related to the Dirichlet-multinomial and NB distributions, and shows how to introduce auxiliary variables to make the likelihood of $\mathbf{z} \sim \text{DirCat}(n, r_1, \dots, r_K)$, as shown in (7), become fully factorized.

Proposition 3. *Given the sample length n (number of customers) and $\mathbf{r} = (r_1, \dots, r_K)$, the joint distribution of the “table” indices $\mathbf{b} = (b_1, \dots, b_n)$ and “dish” indices $\mathbf{z} = (z_1, \dots, z_n)$ in*

$$\{b_i\}_{i:z_i=k} \sim \text{CRP}(n_k, r_k), \quad \mathbf{z} \sim \text{DirCat}(n, r_1, \dots, r_K),$$

is the same as that in

$$z_i = s_{b_i}, \quad s_t \sim \text{Cat}(r_1/r, \dots, r_K/r), \quad \mathbf{b} \sim \text{CRP}(n, r),$$

with PMF

$$P(\mathbf{b}, \mathbf{z} | n, \mathbf{r}) = \frac{\Gamma(r)}{\Gamma(n+r)} \prod_{k=1}^K \left\{ r_k^{\ell_k} \prod_{t=1}^{\ell_k} \Gamma(n_{kt}) \right\},$$

where ℓ_k is the number of unique indices in $\{b_i\}_{i:z_i=k}$, $\ell = \sum_{k=1}^K \ell_k$ is the total number of nonempty tables, $t = 1, \dots, \ell$, and $n_{kt} = \sum_{i=1}^n \delta(b_i = t, z_i = k)$ is the number of customers that sit at table t and take dish k .

If we further randomize the sample length as

$$n \sim \text{NB}(r, p),$$

then we have the PMF for the joint distribution of \mathbf{b} , \mathbf{z} , and n given \mathbf{r} and p in a fully

factorized form as

$$P(\mathbf{b}, \mathbf{z}, n | \mathbf{r}, p) = \frac{1}{n!} \prod_{k=1}^K \left\{ r_k^{\ell_k} (1-p)^{r_k} p^{n_k} \prod_{t=1}^{\ell_k} \Gamma(n_{kt}) \right\},$$

which, with appropriate combinatorial analysis, can be mapped to the PMF of the joint distribution of $\mathbf{n} = (n_1, \dots, n_k)$, $\boldsymbol{\ell} = (\ell_1, \dots, \ell_k)$, and n given \mathbf{r} and p in

$$n = \sum_{k=1}^K n_k, \quad n_k = \sum_{t=1}^{\ell_k} n_{kt}, \quad n_{kt} \sim \text{Logarithmic}(p), \quad \ell_k \sim \text{Pois}[-r_k \ln(1-p)]. \quad (22)$$

Using (16) and Proposition 3, introducing the auxiliary variables

$$\{b_{ji}\}_{i: x_{ji}=v, z_{ji}=k} \sim \text{CRP}(n_{vjk}, \phi_{vk} \theta_{kj}), \quad (23)$$

we have the joint likelihood for the DMMM model as

$$P(\mathbf{b}_j, \mathbf{x}_j, \mathbf{z}_j, n_j | \boldsymbol{\Phi}, \boldsymbol{\theta}_j, p_j) = \frac{1}{n_j!} \prod_v \prod_k \left\{ (\phi_{vk} \theta_{kj})^{\ell_{vjk}} p_j^{n_{vjk}} (1-p_j)^{\phi_{vk} \theta_{kj}} \prod_{t=1}^{\ell_{vjk}} \Gamma(n_{vjkt}) \right\}, \quad (24)$$

where ℓ_{vjk} is the number of unique indices in $\{b_{ji}\}_{i: x_{ji}=v, z_{ji}=k}$ and $n_{vjkt} = \sum_{i=1}^{n_j} \delta(x_{ji} = v, z_{ji} = k, b_{ji} = t)$. As in Proposition 3, instead of first assigning the indices to factors using the Dirichlet-multinomial distributions and then assigning the indices with the same factors to tables, we may first assign the indices to tables and then assign the tables to factors. Thus we have the following model

$$\begin{aligned} x_{ji} &= w_j z_{ji}, \quad z_{ji} = s_j b_{ji}, \quad w_j s_{jt} \sim \text{Cat}(\boldsymbol{\phi}_{s_{jt}}), \quad s_{jt} \sim \text{Cat}(\boldsymbol{\theta}_j / \theta_{.j}), \\ \mathbf{b}_j &\sim \text{CRP}(n_j, \theta_{.j}), \quad n_j \sim \text{NB}(\theta_{.j}, p_j), \end{aligned}$$

whose likelihood $P(\mathbf{b}_j, \mathbf{x}_j, \mathbf{z}_j, n_j | \boldsymbol{\Phi}, \boldsymbol{\theta}_j, p_j)$ is the same as the likelihood, as shown in (24), of the DMMM model constituted of (10) and (12) and augmented with (23).

We outline the collapsed Gibbs sampler for the hGNBP-NBFA in Algorithm 1 and provide the derivation and update equations below. This collapsed sampling strategy marginalizes out both the factors $\{\phi_k\}$ and factor scores $\{\boldsymbol{\theta}_j\}_j$, but at the expense of introducing an auxiliary variable b_{ji} for each index x_{ji} .

Marginalizing out $\boldsymbol{\Phi}$ and $\boldsymbol{\Theta}$ from $\prod_j P(\mathbf{b}_j, \mathbf{x}_j, \mathbf{z}_j, n_j | \boldsymbol{\Phi}, \boldsymbol{\theta}_j, p_j)$, we have

$$\begin{aligned} P(\{\mathbf{b}_j, \mathbf{x}_j, \mathbf{z}_j, n_j\}_j | G, \mathbf{p}) &= e^{r_* \sum_j \ln(1-\tilde{p}_j)} \left\{ \prod_j p_j^{n_j} \frac{\prod_v \prod_k \left(\prod_{t=1}^{\ell_{vjk}} \Gamma(n_{vjkt}) \right)}{n_j!} \right\} \\ &\times \left\{ \prod_{k: \ell_{..k} > 0} \frac{\Gamma(V\eta)}{\Gamma(\ell_{..k} + V\eta)} \prod_{v=1}^V \frac{\Gamma(\ell_{v..k} + \eta)}{\Gamma(\eta)} \right\} \left\{ \prod_j \prod_{k: \ell_{..k} > 0} \frac{\Gamma(r_k + \ell_{.jk})}{\Gamma(r_k)} \frac{c_j^{r_k}}{[c_j - \ln(1-p_j)]^{r_k + \ell_{.jk}}} \right\}, \quad (25) \end{aligned}$$

where $\ell_{..k} := \sum_j \ell_{.jk}$ and $r_\star := \sum_{k: \ell_{..k}=0} r_k$.

Sample z_{ji} and b_{ji} . Using the likelihood in (25), with $(K^+)^{-ji}$ representing the number of active atoms without considering z_{ji} , we have

$$P(z_{ji}=k, b_{ji}=t | x_{ji}, \mathbf{z}^{-ji}, \mathbf{b}^{-ji}, G) \propto \begin{cases} n_{x_{ji}jkt}^{-ji}, & \text{if } k \leq (K^+)^{-ji}, t \leq \ell_{x_{ji}jk}^{-ji}; \\ \frac{\ell_{x_{ji}.k}^{-ji} + \eta}{\ell_{..k}^{-ji} + V\eta} \frac{r_k + \ell_{.jk}^{-ji}}{c_j - \ln(1-p_j)}, & \text{if } k \leq (K^+)^{-ji}, t = \ell_{x_{ji}jk}^{-ji} + 1; \\ \frac{1}{V} \frac{r_\star}{c_j - \ln(1-p_j)}, & \text{if } k = (K^+)^{-ji} + 1, t = 1; \end{cases}$$

and if $k = (K^+)^{-ji} + 1$ happens, similar to the direct assignment sampler for the hierarchical Dirichlet process (Teh et al. 2006), we draw $\beta \sim \text{Beta}(1, \gamma_0)$ and then let $r_k = \beta r_\star$ and $r_\star = (1 - \beta)r_\star$. This is based on the stick-breaking representation of the Dirichlet process, $\tilde{G}_\star \sim \text{DP}(\gamma_0, G_0/\gamma_0)$, whose product with an independent random variable $r_\star \sim \left(\gamma_0, [c_0 - \sum_j \ln(1 - \tilde{p}_j)]^{-1}\right)$ recovers the gamma process $G_\star \sim \text{GP}\left(G_0, [c_0 - \sum_j \ln(1 - \tilde{p}_j)]^{-1}\right)$. Note that instead of drawing both z_{ji} and b_{ji} at the same time, one may first draw z_{ji} and then draw b_{ji} given z_{ji} , or first draw b_{ji} and then draw z_{ji} given b_{ji} . We describe how to sample the other parameters in Appendix C.2.

5.3 Blocked Gibbs sampling under compound Poisson representation

Examining both the blocked and collapsed Gibbs samplers presented Sections 5.1 and 5.2, respectively, and their sampling steps shown in Algorithm 1, one may notice that to obtain n_{vjk} in each iteration, one has to go through all individual indices x_{ji} , for each of which the sampling of z_{ji} from a multinomial distribution takes $O(K)$ computation. However, as it is the ℓ_{vjk} but not n_{vjk} that are required for sampling all the other model parameters, one may naturally wonder whether the step of sampling z_{ji} to obtain n_{vjk} can be skipped. To answer that question, we first introduce the following theorem, whose proof is provided in Appendix A.

Theorem 4. *Conditioning on n and \mathbf{r} , with $\{n_k\}_k$ marginalized out, the distribution of $\ell = (\ell_1, \dots, \ell_k)$ in*

$$\ell_k | n_k \sim \text{CRT}(n_k, r_k), \quad \mathbf{n} | n \sim \text{DirMult}(n, r_1, \dots, r_K)$$

is the same as that in

$$\ell | \ell. \sim \text{Mult}(\ell., r_1/r., \dots, r_K/r.), \quad \ell. | n \sim \text{CRT}(n, r.),$$

with PMF

$$P(\ell | n, r_1, \dots, r_K) = \frac{\ell.!}{\prod_{k=1}^K \ell_k!} \frac{\Gamma(r.)}{\Gamma(n+r.)} |s(n, \ell.)| \prod_{k=1}^K r_k^{\ell_k}.$$

Rather than representing NBFA in (19) as the DMMM model in (18), we may directly consider its compound Poisson representation as

$$n_{vj} = \sum_{t=1}^{\ell_{vj}} n_{vjt}, \quad n_{vjt} \sim \text{Logarithmic}(p_j), \quad \ell_{vj} \sim \text{Pois} \left[- \sum_k \phi_{vk} \theta_{kj} \ln(1 - p_j) \right]. \quad (26)$$

Under this representation, we may first infer ℓ_{vj} for each n_{vj} and then factorize the latent count matrix $\{\ell_{vj}\}_{v,j}$ under the Poisson likelihood, as described below.

Rather than first sampling z_{ji} (and hence n_{vjk}) using (20) and then sampling ℓ_{vjk} using (21), with Theorem 4 and the compound Poisson representation in (26), we can skip sampling z_{ji} and directly sample ℓ_{vjk} as

$$(\ell_{vj} | -) \sim \text{CRT} \left(n_{vj}, \sum_k \phi_{vk} \theta_{kj} \right), \quad (27)$$

$$[(\ell_{vj1}, \dots, \ell_{vjK}) | -] \sim \text{Mult} \left(\ell_{vj}, \frac{\phi_{v1} \theta_{1j}}{\sum_k \phi_{vk} \theta_{kj}}, \dots, \frac{\phi_{vK} \theta_{Kj}}{\sum_k \phi_{vk} \theta_{kj}} \right). \quad (28)$$

All the other model parameters can be sampled in the same way as they are sampled in the regular blocked Gibbs sampler, with (C.1)-(C.2).

Note that $\ell_{vj} = n_{vj}$ a.s. if $n_{vj} \in \{0, 1\}$, $\ell_{vj} \leq n_{vj}$ a.s. if $n_j \geq 2$, and

$$\mathbb{E}[\ell_{vj} | n_{vj}, \phi_{vk} \theta_{kj}] = (\sum_k \phi_{vk} \theta_{kj}) [\psi(n_{vj} + \phi_{vk} \theta_{kj}) - \psi(\phi_{vk} \theta_{kj})],$$

where $\psi(x) = \frac{d}{dx} \ln \Gamma(x)$ is the digamma function. Thus $\mathbb{E}[\ell_{vj}] \approx (\sum_k \phi_{vk} \theta_{kj}) \ln(n_{vj})$ when n_{vj} is large. Clearly, this new sampling strategy significantly impacts n_{vj} that are large. In comparison to the regular blocked Gibbs sampler described in detail in Section 5.1, the compound Poisson based blocked Gibbs sampler essentially replaces (20)-(21) of the regular one with (27)-(28), which can be readily justified by Theorem 4. Instead of directly assigning the n_{vj} covariate indices to the K latent factors, now we only need to assign them to $O[\ln(n_{vj} + 1)]$ tables and directly assign these tables to latent factors. As assigning an index to a table can be accomplished by just a single Bernoulli random draw, this new sampling procedure reduces the computational complexity for sampling all ℓ_{vjk} from $O(n..K)$ to $O[\sum_v \sum_j \ln(n_{vj} + 1)K]$, which could lead to a considerable saving in computation for long samples where large counts n_{vj} are abundant.

This new sampling algorithm not only is less expensive in computation, but also may converge much faster as there is no need to worry about the dependencies between the MCMC samples for the factor indices z_{ji} , which are not used at all under the compound Poisson representation. Note that the collapsed Gibbs sampler in Section 5.2 removes the need to sample Φ and Θ at the expense of having to sample z_{ji} and augment a b_{ij} for each z_{ij} . We will show in Appendix F that maintaining Φ and Θ but removing the need to sample z_{ji} leads to a more effective sampler.

5.4 Model comparison

We also consider NBFA based on the GNBP, in which each of the J samples is assigned with a sample-specific NB process and a globally shared gamma process is mixed with

Table 2: Comparisons of the GNBP-PFA, GNBP-DCMLDA, and hGNBP-NBFA.

	GNBP-PFA (multinomial mixed-membership model)	GNBP-DCMLDA	hGNBP-NBFA (Dirichlet-multinomial mixed-membership model)
Estimated Poisson rate of n_{vj} given the factors and factor scores	$\sum_k \phi_{vk} \theta_{kj}$	$(n_{vj} + \sum_k \phi_{vk} r_k) p_j$	$(n_{vj} + \sum_k \phi_{vk} \theta_{kj}) p_j$
Factor analysis	$\mathbf{n}_j \sim \text{Pois}(\Phi \theta_j)$	$\mathbf{n}_j \sim \text{NB}(\Phi \mathbf{r}, p_j)$	$\mathbf{n}_j \sim \text{NB}(\Phi \theta_j, p_j)$
Mixed-membership modeling	$z_{ji} \sim \text{Cat}(\theta_j / \theta_{.j}),$ $x_{ji} \sim \text{Cat}(\phi_{z_{ji}})$	$\theta_j \sim \text{Dir}(\mathbf{r}),$ $z_{ji} \sim \text{Cat}(\theta_j),$ $\phi_k^{[j]} \sim \text{Dir}(\phi_k r_k),$ $x_{ji} \sim \text{Cat}(\phi_{z_{ji}}^{[j]})$	$\theta^{[j]} \sim \text{Dir}(\theta_j),$ $z_{ji} \sim \text{Cat}(\theta^{[j]}),$ $\phi_k^{[j]} \sim \text{Dir}(\phi_k \theta_{kj}),$ $x_{ji} \sim \text{Cat}(\phi_{z_{ji}}^{[j]})$
Distribution of $X_j = \sum_{k=1}^{\infty} n_{.jk} \delta_{\phi_k}$ given G	$X_j G, p_j \sim$ NBP(G, p_j)	$X_j G, p_j \sim$ NBP(G, p_j)	$X_j G, c_j, p_j \sim$ GNBP(G, c_j, p_j)
Variance-to-mean ratio of $n_{.jk}$ given c_j and p_j	$\frac{1}{1-p_j}$	$\frac{1}{1-p_j}$	$\frac{1}{1-p_j} + \frac{p_j}{c_j(1-p_j)^2}$

all the J NB processes. Given its connection to DCMLDA, as revealed in Section 3.3, we call this nonparametric Bayesian model as the GNBP-DCMLDA, which is shown to be restrictive in that although each sample has its own factor scores under the corresponding sample-specific factors, all the samples are enforced to have the same factor scores under the same set of globally shared factors. By contrast, by modeling not only the burstiness of the covariates, but also that of the factors, the hGNBP-NBFA provides sample-specific factor scores under the same set of shared factors, making it suitable for extracting low-dimensional latent representations for high-dimensional covariate count vectors.

We describe in detail in Appendix D how to use the gamma-negative binomial process (GNBP) as a nonparametric Bayesian prior for both PFA and DCMLDA. In the prior, for PFA, we have $n_{vj} \sim \text{Pois}(\sum_k \phi_{vk} \theta_{kj})$, whereas for NBFA, we have $n_{vj} \sim \text{NB}(\sum_k \phi_{vk} \theta_{kj}, p_j)$, which can be augmented as

$$n_{vj} \sim \text{Pois}(\lambda_{vj}), \quad \lambda_{vj} \sim \text{Gamma}[\sum_k \phi_{vk} \theta_{kj}, p_j / (1 - p_j)].$$

Thus we have $(\lambda_{vj} | n_{vj}, \Phi, \theta_j, p_j) \sim \text{Gamma}(n_{vj} + \sum_k \phi_{vk} \theta_{kj}, p_j)$ for NBFA. Similarly, we have $(\lambda_{vj} | -) \sim \text{Gamma}(n_{vj} + \sum_k \phi_{vk} r_k, p_j)$ for the GNBP-DCMLDA. To better understand the similarities and differences between the GNBP-PFA, GNBP-DCMLDA, and hGNBP-NBFA, in Table 2 we compare their Poisson rates of n_{vj} , estimated with the factors and factor scores in a single MCMC sample, and several other important model properties.

To estimate the latent Poisson rates for each count n_{vj} and hence the smoothed normalized covariate frequencies, it is clear from the second row of Table 2 that PFA (the multinomial mixed-membership model) solely relies on the inferred factors $\{\phi_k\}$ and factor scores $\{\theta_{kj}\}$, DCMLDA adds a sample-invariant smoothing parameter, calculated

as $\sum_v \phi_{vk} r_k$, into the observed count n_{vj} and weights that sum by a sample-specific probability parameter p_j , whereas NBFA (the DMMM model) adds a sample-specific smoothing parameter, calculated as $\sum_v \phi_{vk} \theta_{kj}$, into the observed count n_{vj} and weights that sum by p_j . Thus PFA represents an extreme that the observed counts are used to infer the factors and factor scores but are not used to directly estimate the Poisson rates; DCMLDA represents another extreme that the covariate frequencies in all samples are indiscriminately smoothed by the same set of smoothing parameters; whereas NBFA combines the observed counts with the inferred sample-specific smoothing parameters. This unique working mechanism also makes NBFA have reduced hyper-parameter sensitivity, as will be demonstrated with experiments.

6 Example Results

We apply the proposed models to factorize covariate-sample count matrices, each column of which is represented as a V dimensional covariate-frequency count vector, where V is the number of unique covariates. We set the hyper-parameters as $a_0 = b_0 = 0.01$ and $e_0 = f_0 = 1$. We consider the JACM (<http://www.cs.princeton.edu/~blei/downloads/>), Psychological Review (PsyReview, <http://psiexp.ss.uci.edu/research/programs.data/toolbox.htm>), and NIPS12 (<http://www.cs.nyu.edu/~roweis/data.html>) datasets, choosing covariates that occur in five or more samples. In addition, we consider the 20newsgroups dataset (<http://qwone.com/~jason/20Newsgroups/>), consisting of 18,774 samples from 20 different categories. It is partitioned into a training set of 11,269 samples and a testing set of 7,505 ones that were collected at later times. We remove a standard list of stopwords and covariates that appear less than five times. As summarized in Table 3 of Appendix G, for the PysReview and JACM datasets, each of whose sample corresponds to the abstract of a research paper, the average sample lengths are only about 56 and 127, respectively. By contrast, a NIPS12 sample that includes the words of all sections of a research paper is in average more than ten times longer. By varying the percentage of covariate indices randomly selected from each sample for training, we construct a set of covariate-sample matrices with a large variation on the average lengths of samples, which will be used to help make comparison between different models. Depending on applications, we either treat the Dirichlet smoothing parameter η as a tuning parameter, or sample it via data augmentation, as described in Appendix E.

To learn the factors in all the following experiments, we use the compound Poisson representation based blocked Gibbs sampler for both the hGNBP-NBFA and GNBP-NBFA, and use collapsed Gibbs sampling for the GNBP-PFA. We compare different samplers for the hGNBP-NBFA and provide justifications for choosing these samplers in Appendix F.

6.1 Prediction of heldout covariate indices

Experimental settings

We randomly choose a certain percentage of the covariate indices in each sample as training, and use the remaining ones to calculate heldout perplexity. As shown in Zhou and Carin (2015), the GNB-PFA performs similarly to the hierarchical Dirichlet process LDA of Teh et al. (2006) and outperforms a wide array of discrete latent variable models, thus we choose it for comparison. To demonstrate the importance of modeling both the burstiness of the covariates and that of the factors, we also make comparison to the GNB-DCMLDA that considers only covariate burstiness. Since the inferred number of factors and hence the performance often depends on the Dirichlet smoothing parameter η , we set η as 0.005, 0.02, 0.01, 0.05, 0.10, 0.25, or 0.50. We vary both the training percentage and η to examine how the average sample length and the value of η influence the behaviors of the GNB-PFA, GNB-DCMLDA, and hGNB-NBFA and impact their performance relative to each other.

For all three algorithms, we initialize the number of factors as $K = 400$ and consider 5000 Gibbs sampling iterations, with the first 2500 samples discarded and every sample per five iterations collected afterwards. For each collected sample, for the GNB-PFA, we draw the factors $(\phi_k | -) \sim \text{Dir}(\eta + n_{1.k}, \dots, \eta + n_{V.k})$ and factor scores $(\theta_{kj} | -) \sim \text{Gamma}(n_{jk} + r_k, p_j)$ for $k \in \{1, \dots, K^+ + K_\star\}$, where we let $n_{v.k} = 0$ for all $k > K^+$; for the GNB-DCMLDA, we draw the factors $(\phi_k | -) \sim \text{Dir}(\eta + \ell_{1.k}, \dots, \eta + \ell_{V.k})$ and the weights $(r_k | -) \sim \text{Gamma}(\ell_{.k}, 1/[c_0 - \sum_j \ln(1 - p_j)])$, where we let $\ell_{v.k} = 0$ and $\ell_{.k} = \gamma_0/K_\star$ for all $k > K^+$; and for the hGNB-NBFA, we draw the factors $(\phi_k | -) \sim \text{Dir}(\eta + \ell_{1.k}, \dots, \eta + \ell_{V.k})$ and factor scores $(\theta_{kj} | -) \sim \text{Gamma}[r_k + \ell_{.jk}, 1/(c_j - \ln(1 - p_j))]$, where we let $\ell_{v.k} = 0$ and $r_k = \gamma_0/K_\star$ for all $k > K^+$. We set $K_\star = 20$ for all three algorithms.

We compute the heldout perplexity as

$$\exp \left(-\frac{1}{m_{..}^{\text{test}}} \sum_v \sum_j m_{vj}^{\text{test}} \ln \frac{\sum_s \lambda_{vj}^{(s)}}{\sum_s \sum_{v'} \lambda_{v'j}^{(s)}} \right),$$

where $s \in \{1, \dots, S\}$ is the index of a collected MCMC sample, m_{vj}^{test} is the number of test covariate indices at covariate v in sample j , $m_{..}^{\text{test}} = \sum_v \sum_j m_{vj}^{\text{test}}$, and $\lambda_{vj}^{(s)}$ are computed using the equations shown in the second row of Tabel 2, *e.g.*, we have $\lambda_{vj}^{(s)} = \left(n_{vj} + \sum_{k=1}^{K^+ + K_\star} \phi_{vk}^{(s)} \theta_{kj}^{(s)} \right) p_j^{(s)}$ for the hGNB-NBFA. For each unique combination of η and the training percentage, the results are averaged over five random training/testing partitions. The evaluation method is similar to those used in Wallach et al. (2009b), Paisley et al. (2012), and Zhou and Carin (2015). All algorithms are coded in MATLAB, with the steps of sampling factor and table indices coded in C to optimize speed. We terminate a trial and omit the results for that particular setting if it takes a single core of an Intel Xeon 3.3 GHz CPU more than 24 hours to finish 5000 iterations. The code will be made available in the author's website for reproducible research.

We first consider the NIPS12 dataset, whose average sample length is about 1323, and present its results in Figures 2-5. We also consider both the PsyReview and JACM datasets, whose average sample lengths are about 56 and 127, respectively, and provide related plots in Appendix G.

General observations

For multinomial mixed-membership models, generally speaking, the smaller the Dirichlet smoothing parameter η is, the more sparse and specific the inferred factors are encouraged to be, and the larger the number of inferred factors using a nonparametric Bayesian mixed-membership modeling prior, such as the hierarchical Dirichlet process and the gamma- and beta-negative binomial processes (Paisley et al. 2012; Zhou et al. 2012). As shown in Figures 2(a)-(e), for the hGNBP-NBFA, a nonparametric Bayesian DMMM model, we observe a relationship between the number of inferred factors and η similar to that for the GNBP-PFA, a nonparametric Bayesian multinomial mixed-membership model.

In comparison to multinomial mixed-membership models such as the GNBP-PFA, what make the hGNBP-NBFA different and desirable are: 1) its parsimonious representation that uses fewer factors to achieve better heldout prediction, as shown in Figures 3(a)-(e); 2) its distinct mechanism in adjusting its number of inferred factors according to the lengths of samples, as shown in Figures 4(a)-(f); 3) its significantly lower computational complexity for a covariate-sample matrix with long samples (large column sums), with the differences becoming increasingly more significant as the average sample length increases, as shown in Figures 3(f)-(j) and 5(a)-(f); 4) its ability to achieve the same predictive power with significantly less time, as shown in Figures 5(g)-(l); 5) and its overall better predictive performance both under various values of η while controlling the sample lengths, as shown in Figures 2(f)-(j), and under various sample lengths while controlling η , as shown in Figures 4(g)-(l).

Detailed discussions

Distinct behavior and parsimonious representation. When fixing η but gradually increasing the average sample length, the number of factors inferred by a nonparametric Bayesian multinomial mixed-membership model such as the GNBP-PFA often increases at a near-constant rate, as shown with the blue curves in Figure 4(a)-(f). The GNBP-DCMLDA, which models covariate burstiness, behaves similarly in the number of inferred factors, as shown with the red curves in Figure 4(a)-(f). Under the same setting, the number of inferred factors by the hGNBP-NBFA often first increases at a similar near-constant rate when the average sample length is short, however, it starts decreasing once the average sample length becomes sufficiently long, and eventually turns around and increases, but at a much lower rate, as the average sample length further increases, as shown with the yellow curves in Figure 4(a)-(f). This distinct behavior implies that by exploiting its ability to model both covariate and factor burstiness, the hGNBP-NBFA could have a parsimonious representation of a dataset with long samples. By contrast, a nonparametric Bayesian multinomial mixed-membership model, such as the GNBP-

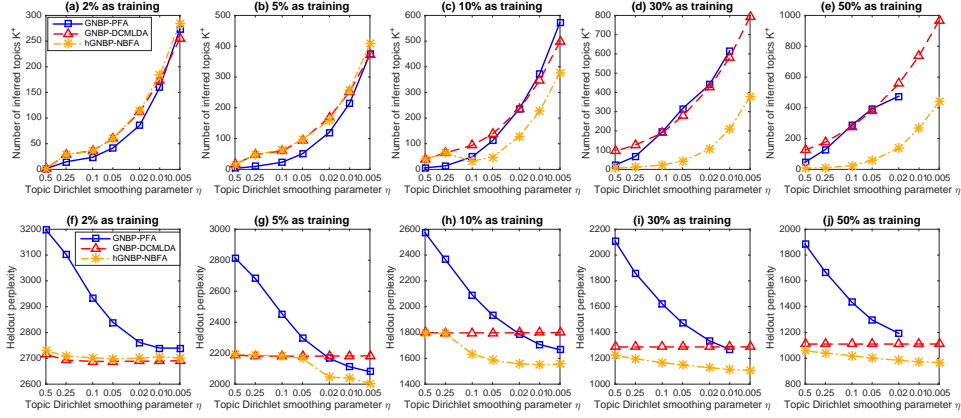


Figure 2: Comparisons of the GNPB-PFA (multinomial mixed-membership model), GNPB-DCMLDA, and hGNBP-NBFA (Dirichlet-multinomial mixed-membership model) on (a)-(e) the posterior means of the number of inferred factors K^+ and (f)-(j) heldout perplexity, both as a function of the Dirichlet smoothing parameter η for the NIPS12 dataset. The values of η are plot in the logarithmic scale from large to small. In both rows, the plots from left to right are obtained using 2%, 5%, 10%, 30%, and 50% of the covariate indices for training, respectively. All plots are based on five independent random trials. The error bars are not shown as variations across different trials are small. Some results for the GNPB-PFA are missing as they took more than 24 hours to run 5000 Gibbs sampling iterations on a 3.3 GHz CPU and hence were terminated before completion.

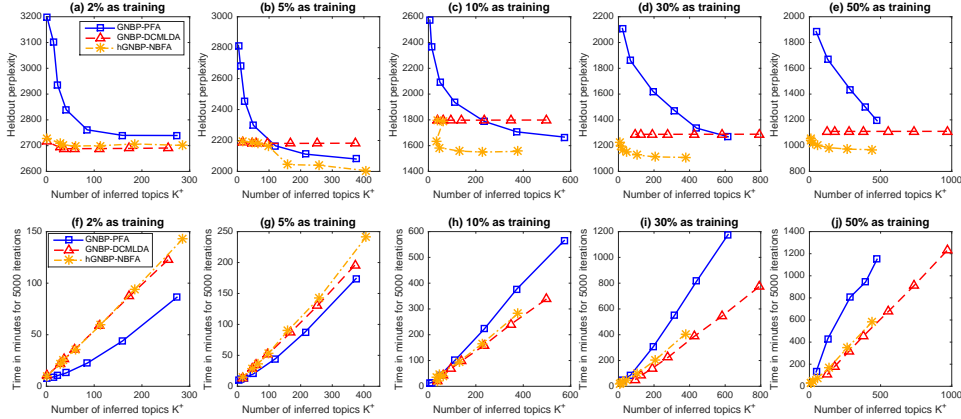


Figure 3: Using the same results shown in Figure 2, we plot (a)-(e) the obtained heldout perplexity and (f)-(j) the number of minutes to finish 5000 Gibbs sampling iterations, both as a function of the number of inferred factors K^+ .

PFA, models neither covariate nor factor burstiness. Consequently, it has to increase its latent dimension at a near-constant rate as a function of the average sample length, in order to adequately capture self- and cross-excitation of covariate frequencies, which are often more prominent in longer samples. It is clear that by decreasing η and hence

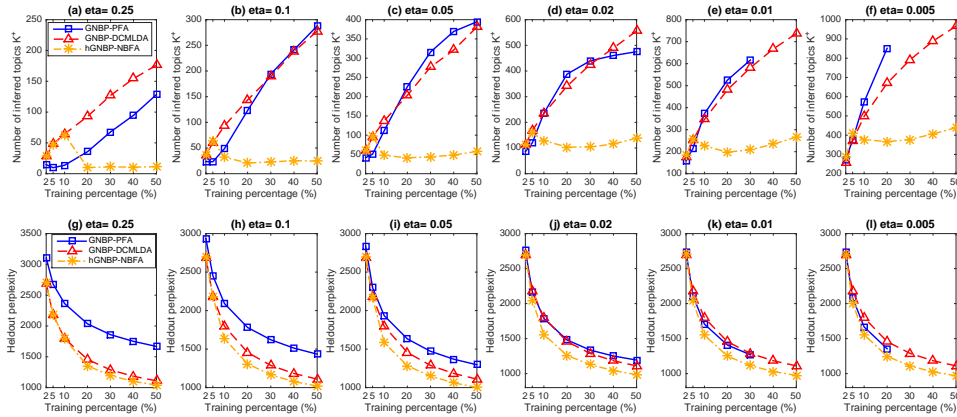


Figure 4: Comparisons of the GNPB-PFA (multinomial mixed-membership model), GNPB-DCMLDA, and hGNBP-NBFA (Dirichlet-multinomial mixed-membership model) on (a)-(f) the posterior means of the number of inferred factors K^+ and (g)-(l) heldout perplexity, both as a function of the percentage of covariate indices used for training for the NIPS12 dataset. In both rows, the plots from left to right are obtained with $\eta = 0.25, 0.1, 0.05, 0.02, 0.01$, and 0.005 , respectively. Other specifications are the same as those of Figure 2.

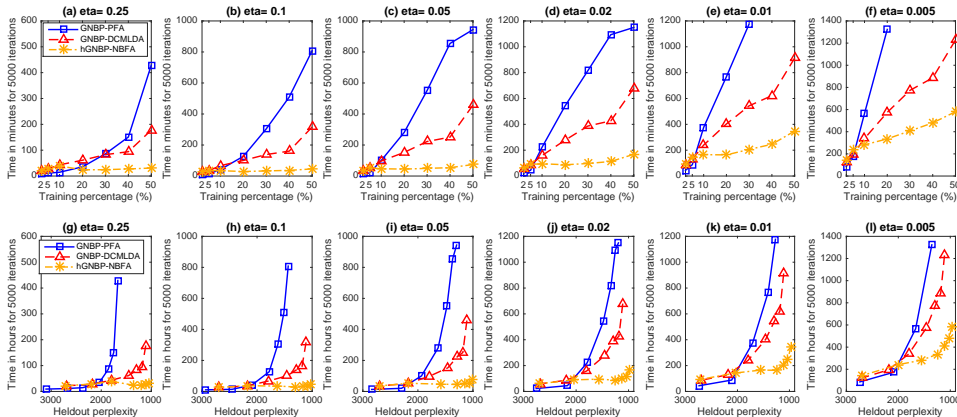


Figure 5: Using the results shown in Figure 4, we plot the number of minutes to finish 5000 Gibbs sampling iterations both (a)-(f) as a function of the percentage of covariates used for training and (g)-(l) as a function of heldout perplexity.

increasing the number of inferred factors, the GNPB-PFA can gradually approach and eventually outperform the GNPB-DCMLDA, but still clearly underperform the hGNBP-NBFA in most cases, even if using many more factors and consequently significantly more computation.

Combining factorization and the modeling of burstiness. As shown in Figure 2(f), when the training percentage is as small as 2%, the GNPB-DCMLDA, which combines the observed counts n_{vj} and the inferred sample-invariant smoothing parameters

$\sum_k \phi_{vk} r_k$ to estimate the Poisson rates (and hence the smoothed normalized covariate frequencies), achieves the best predictive performance (lowest heldout perplexity); the hGNBP-NBFA tries to improve DCMLDA by combining the observed counts and document-specific smoothing parameters $\sum_k \phi_{vk} \theta_{kj}$, and the GNB-PFA only relies on $\sum_k \phi_{vk} \theta_{kj}$, yielding slightly and significantly worse performance, respectively, at this relatively extreme setting. This suggests that when the observed counts are too small, using factorization may not provide any advantages than simply smoothing the raw covariate counts with sample-invariant smoothing parameters.

As the training percentage increases, all three algorithms quickly improve their performance, as shown in Figures 2(g)-(j). Given a training percentage that is sufficiently large, e.g., 10% for this dataset (*i.e.*, the average training sample length is about 132), all three algorithms tend to increase their numbers of inferred factors K^+ as η decreases, although the hGNBP-NBFA usually has a lower increasing rate. They differ from each other significantly, however, on how the performance improves as the inferred number factors increases, as shown in Figures 3(a)-(e): for the GNB-DCMLDA, as it relies on $\sum_k \phi_{vk} r_k$ to smooth the observed counts, its predictive power is almost invariant to the change of η and its number of factors; for the GNB-PFA, by decreasing η and hence increasing its number of inferred factors, it can approach and eventually outperform DCMLDA; whereas for the hGNBP-NBFA, it follows DCMLDA closely when η is large or the lengths of samples are short, but often reduces its rate of increase for the number of inferred factors as η decreases and quickly lowers its perplexity as K^+ increases, as long as η is sufficiently small or the samples are sufficiently long. Thus in general, the hGNBP-NBFA provides the lowest perplexity using the least number of inferred factors.

Note that when the lengths of the training samples are short, setting η to be large will make the factors ϕ_k of NBFA become over-smoothed and hence NBFA becomes essentially the same as DCMLDA. As η decreases given the same average sample length, or as the average sample length increases given the same η , the factorization of NBFA with sample-dependent factor scores gradually take effect to improve the estimation of the Poisson rates and hence the smoothed normalized covariate frequencies for each sample. Overall, by combining the factorization, as used in PFA, the modeling of covariate burstiness, as used in DCMLDA, and the modeling of factor burstiness, unique to NBFA, the hGNBP-NBFA captures both self- and cross-excitation of covariate frequencies and achieves the best predictive performance with the most parsimonious representation as long as the average sample length is not too short and the value of η is not set too large to overly smooth the factors.

Significantly lower computation for sufficiently long samples. For the GNB-PFA, the collapsed Gibbs sampler samples all the factor indices with a computational complexity of $O(n..K^+)$, whereas for the hGNBP-NBFA, the corresponding computation has a complexity of $O[\sum_v \sum_j \ln(n_{vj} + 1)K^+]$ and sampling $\{\phi_k\}_k$ and $\{\theta_j\}_j$ adds an additional computation of $O(VK^+ + NK^+)$. Thus the computation for the hGNBP-NBFA not only is often lower given the same K^+ for a dataset consisting of sufficiently long samples, but also becomes much lower because the inferred K^+ is often much smaller when the sample lengths are sufficiently long. For example, as shown in

Figure 3(i), when 30% of the covariate indices in each sample are used for training, which means the average training sample length is about 397, the time for the GNB-PFA to finish 5000 Gibbs sampling iteration on a 3.3 GHz CPU is about double that for the hGNBP-NBFA when their inferred numbers of factors are similar to each other; and when 20% of the covariate indices in each sample are used for training (*i.e.*, the average training sample length is around 265), in comparison to the hGNBP-NBFA, the GNB-PFA takes about three times more minutes when $\eta = 0.1$, as shown in Figures 5(b), and four times more minutes when $\eta = 0.01$, as shown in Figures 5(e). Overall, for a dataset whose samples are not too short to exhibit self- and cross-excitation of covariate frequencies, the hGNBP-NBFA often takes the least time to finish the computation while controlling the value of η and average sample length, has lower computation given the same inferred number of factors K^+ , and achieves a low perplexity with significantly less computation.

6.2 Unsupervised feature learning for classification

To further verify the advantages of NBFA that models both self- and cross-excitation of covariate frequencies, we use the proposed models to extract low-dimensional feature vectors from high-dimensional covariate-frequency count vectors of the 20news-groups dataset, and then examine how well the unsupervisedly extracted feature vector of a test sample can be used to correctly classify it to one of the 20 news groups. As the classification accuracy often strongly depends on the dimension of the feature vectors, we truncate the total number of factors at $K = 25, 50, 100, 200, 400, 600, 800,$ or 1000. Correspondingly, we slightly modify the gamma process based nonparametric Bayesian models by choosing a discrete base measure for the gamma process as $G_0 = \sum_{k=1}^K \frac{\gamma_0}{K} \delta_{\phi_k}$, $\phi_k \sim \text{Dir}(\eta, \dots, \eta)$. Thus in the prior we now have $r_k = G(\phi_k) \sim \text{Gamma}(\gamma_0/K, 1/c_0)$ and consequently the Gibbs sampling update equations for $\{r_k\}_k$ and γ_0 will also slightly change. We omit these details for brevity, and refer to Zhou and Carin (2015) on how the same type of finite truncation is used in inference for nonparametric Bayesian models.

For this application, we fix the truncation level K but impose the non-informative $\text{Gamma}(0.01, 1/0.01)$ prior on the Dirichlet smoothing parameter η , letting it be inferred from the data using (E.2). The same as before, we consider collapsed Gibbs sampling for the GNB-PFA and the compound Poisson representation based blocked Gibbs sampler for the hGNBP-NBFA, with the main difference in that a fixed instead of an adaptive truncation is now used for inference. We do not consider the GNB-DCMLDA here since it does not provide sample specific feature vectors under the same set of shared factors. Note that although we fix K , if K is set to be large enough, not necessarily all factors would be used and hence a truncated model still preserves its ability to infer the number of active factors $K^+ \leq K$; whereas if K is set to be small, a truncated model may lose its ability to infer K^+ , but it still maintains asymmetric priors (Wallach et al. 2009a) on the factor scores.

For both the hGNBP-NBFA and GNB-PFA, we consider 2000 Gibbs sampling iterations on the 11,269 training samples of the 20news-groups dataset, and retain the

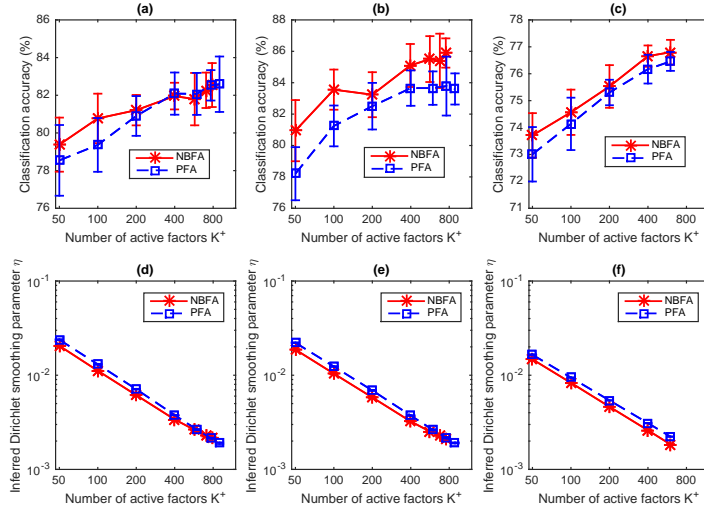


Figure 6: Comparison between negative binomial factor analysis (NBFA) and Poisson factor analysis (PFA) on three different classification tasks, with the number of factors K fixed and the Dirichlet smoothing parameter η inferred from the data. For the *alt.atheism* versus *talk.religion.misc* binary classification task, based on twelve independent random trials, we plot (a) the classification accuracy and (d) the inferred η , both as a function of the number active topics $K^+ \leq K$, where $K \in \{50, 100, 200, 400, 600, 800, 1000\}$. (d) and (e): Analogous plots to (a) and (b) for the *comp.sys.ibm.pc.hardware* versus *comp.sys.mac.hardware* binary classification task, with $K \in \{50, 100, 200, 400, 600, 800, 1000\}$. (c) and (f): Analogous plots to (a) and (b) for the 20newsgroups multi-class classification task, with $K \in \{50, 100, 200, 400, 600\}$.

weights $\{r_k\}_{1,K}$ and the posterior means of $\{\phi_k\}_{1,K}$ as factors, according to the last MCMC sample, for testing. With these K inferred factors and weights, we further apply 1000 blocked Gibbs sampling iterations for both models and collect the last 500 MCMC samples to estimate the posterior mean of the feature usage proportion vector $\theta_j/\theta_{\cdot j}$, for every sample in both the training and testing sets. Denote $\bar{\theta}_j \in \mathbb{R}^K$ as the estimated feature vector for sample j . We use the L_2 regularized logistic regression provided by the LIBLINEAR (<https://www.csie.ntu.edu.tw/~cjlin/liblinear/>) package (Fan et al. 2008) to train a linear classifier on all $\bar{\theta}_j$ in the training set and use it to classify each $\bar{\theta}_j$ in the test set to one of the 20 news groups; the regularization parameter C of the classifier five-fold cross validated on the training set from $(2^{-10}, 2^{-9}, \dots, 2^{15})$.

We first consider distinguishing between the *alt.atheism* and *talk.religion.misc* news groups, and between the *comp.sys.ibm.pc.hardware* and *comp.sys.mac.hardware* news groups. For each binary classification task, we remove a standard list of stop words and only consider the covariates that appear at least five times in both newsgroups combined, and report the classification accuracies based on twelve independent runs with random initializations. For the first binary classification task, we have 856 training documents, with 6509 unique terms and about 116K words, while for the second one, we have 1162 training documents, with 4737 unique terms and about 91K words.

As shown in Figures 6(a) and 6(b), NBFA clearly outperforms PFA for both binary

classification tasks in that it in general provides higher classification accuracies on testing samples while controlling the truncation level K (*i.e.*, the dimension of the extracted feature vectors). It is also interesting to examine how the inferred Dirichlet smoothing parameter η changes as the truncation level K increases, as shown in Figures 6(d) and 6(e). It appears that the inferred η 's and active factors K^+ 's could be fitted with a decreasing straight line in the logarithmic scale, except for the tails that seem slightly concave up, for both NBFA and PFA. When the truncation level K is not sufficiently large, the inferred η of NBFA is usually smaller than that of PFA given the same K . This may be explained by examining (E.2), where $\ell_{vjk} \leq n_{vjk}$ a.s. and the differences could be significant for large n_{vjk} . Note when using the raw word counts as the features, the classification accuracies of logistic regression are 79.4% and 86.7% for the first and second binary classification tasks, respectively, and when using the normalized term frequencies as the features, these are 80.8% and 88.0%, respectively.

In addition to these two binary classification tasks, we consider multi-class classification on the 20newsgroups dataset. After removing stopwords and terms (covariates) that appear less than five times, we obtain 33,420 unique terms and about 1.4 million words for training, as summarized in Table 3. We use all 11,269 training documents to infer the factors and factor scores, and mimic the same testing procedure used for binary classification to extract low-dimensional feature vectors, with which each testing sample is classified to one of the 20 news groups using the same L_2 regularized logistic regression. Note the classification accuracies of logistic regression with the raw counts or normalized term frequencies as features are 78.0% and 79.4%, respectively. As shown in Figure 6(f), NBFA generally outperforms PFA in terms of classification accuracies given the same feature dimensions, consistent with our observations for both binary classification tasks. We also observe similar relationship between the K^+ and inferred η as we do in both binary classification tasks.

7 Conclusions

Negative binomial factor analysis (NBFA) is proposed to factorize the covariate-sample count matrix under the NB likelihood. Its equivalent representation as the Dirichlet multinomial mixed-membership model reveals its distinctions from previously proposed discrete latent variable models. The hierarchical gamma-negative binomial process (hGNBP) is further proposed to support NBFA with countably infinite factors, and a compound Poisson representation based blocked Gibbs sampler is shown to converge fast and have low computational complexity. By capturing both self- and cross-excitation of covariate frequencies and by smoothing the observed counts with both sample and covariate specific rates obtained through factorization under the NB likelihood, the hGNBP-NBFA not only infers a parsimonious representation of a covariate-sample count matrix, but also achieves state-of-the-art predictive performance at low computational cost. In addition, the latent feature vectors inferred under the hGNBP-NBFA are better suited for classification than those inferred by the GNBP-PFA. It is of interest to investigate a wide variety of extensions built on Poisson factor analysis under this new modeling framework.

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Nonparametric Bayesian Negative Binomial Factor Analysis: Supplementary Material

A Proofs

Proof of Theorem 1. With $\mathbf{t} := (t_0, \dots, t_K) \in \mathbb{R}^{K+1}$, the characteristic function of \mathbf{x} can be expressed as

$$\mathbb{E} \left[e^{i\mathbf{t}^T \mathbf{x}} \right] = \prod_{k=1}^K \mathbb{E} \left[e^{i(t_0+t_k)x_k} \right] = \prod_{k=1}^K \left(\frac{1-p}{1-pe^{i(t_0+t_k)}} \right)^{r_k}.$$

We augment \mathbf{y} as

$$(y_1, \dots, y_K) \sim \text{Mult}(y, \boldsymbol{\theta}), \quad \boldsymbol{\theta} \sim \text{Dir}(r_1, \dots, r_K), \quad y \sim \text{Pois}(\lambda), \quad \lambda \sim \text{Gamma}(r, p/(1-p)),$$

where $\boldsymbol{\theta} = (\theta_1, \dots, \theta_K)^T$. Conditioning on $\boldsymbol{\theta}$ and y , we have

$$\mathbb{E} \left[e^{i\mathbf{t}^T \mathbf{y}} \mid \boldsymbol{\theta}, y \right] = \left(\sum_{k=1}^K \theta_k e^{i(t_0+t_k)} \right)^y;$$

conditioning on $\boldsymbol{\theta}$ and λ , we have

$$\begin{aligned} \mathbb{E} \left[e^{i\mathbf{t}^T \mathbf{y}} \mid \boldsymbol{\theta}, \lambda \right] &= \mathbb{E}_y \left[\left(\sum_{k=1}^K \theta_k e^{i(t_0+t_k)} \right)^y \right] \\ &= \exp \left[\lambda \left(\sum_{k=1}^K \theta_k e^{i(t_0+t_k)} - 1 \right) \right] \\ &= \prod_{k=1}^K e^{\lambda_k (e^{i(t_0+t_k)} - 1)}, \end{aligned}$$

where $\lambda_k = \lambda \theta_k$ are independent gamma random variables, as the independent product of the gamma random variable λ and the Dirichlet random vector $\boldsymbol{\theta}$, with the gamma shape parameter and Dirichlet concentration parameter both equal to r , leads to independent gamma random variables. Further marginalizing out λ_k , we have

$$\mathbb{E} \left[e^{i\mathbf{t}^T \mathbf{y}} \right] = \left[1 - \frac{p}{1-p} \left(e^{i(t_0+t_k)} - 1 \right) \right]^{-r_k} = \prod_{k=1}^K \left(\frac{1-p}{1-pe^{i(t_0+t_k)}} \right)^{r_k}.$$

Thus \mathbf{x} and \mathbf{y} are equal in distribution as their characteristic functions are the same. \square

Proof of Proposition 2. Multiplying the likelihood in (11) with the PMF of the NB distribution in (12), we have

$$P(\mathbf{x}_j, \mathbf{z}_j, n_j | \Phi, \theta_j, p_j) = \frac{1}{n_j!} \prod_{v=1}^V \prod_{k=1}^K \frac{\Gamma(n_{vjk} + \phi_{vk} \theta_{kj})}{\Gamma(\phi_{vk} \theta_{kj})} p_j^{n_{vjk}} (1-p_j)^{\phi_{vk} \theta_{kj}},$$

which, multiplied by the combinatorial coefficient $n_j! / (\prod_{v=1}^V \prod_{k=1}^K n_{vjk}!)$, becomes the same as (13). \square

Proof of Proposition 3. For the first hierarchical model, we have

$$\begin{aligned} P(\mathbf{b}, \mathbf{z} | n, \mathbf{r}, p) &= \left\{ \prod_{k=1}^K \text{CRP}(\{b_i\}_{i:z_i=k}; n_k, r_k) \right\} \text{DirCat}(\mathbf{z}; n, \mathbf{r}) \\ &= \frac{\Gamma(r.)}{\Gamma(n+r.)} \prod_{k=1}^K \text{CRP}(\{b_i\}_{i:z_i=k}; n_k, r_k) \frac{\Gamma(n_k + r_k)}{\Gamma(r_k)} \\ &= \frac{\Gamma(r.)}{\Gamma(n+r.)} \prod_{k=1}^K \left\{ r_k^{\ell_k} \prod_{t=1}^{\ell_k} \Gamma(n_{kt}) \right\}, \end{aligned}$$

where ℓ_k is the number of unique indices in $\{b_i\}_{i:z_i=k}$ and $n_{kt} = \sum_{i=1}^n \delta(b_i = t, z_i = k)$.

For the second hierarchical model, we have

$$\begin{aligned} P(\mathbf{b}, \mathbf{z} | n, \mathbf{r}, p) &= P(\mathbf{z} | \mathbf{b}, \mathbf{r}) \text{CRP}(\mathbf{b}; n, r.) \\ &= P(\mathbf{z} | \mathbf{b}, \mathbf{r}) r.^{\ell} \frac{\Gamma(r.)}{\Gamma(n+r.)} \prod_{t=1}^{\ell} \Gamma\left(\sum_{i=1}^n \delta(b_i = t)\right) \\ &= \frac{\Gamma(r.)}{\Gamma(n+r.)} \left\{ \prod_{k=1}^K r_k^{\sum_{t=1}^{\ell} \delta(s_t=k)} \right\} \left\{ \prod_{t=1}^{\ell} \Gamma\left(\sum_{i=1}^n \delta(b_i = t)\right) \right\} \\ &= \frac{\Gamma(r.)}{\Gamma(n+r.)} \prod_{k=1}^K \left\{ r_k^{\ell_k} \prod_{t=1}^{\ell_k} \Gamma(n_{kt}) \right\}, \end{aligned}$$

where $\ell_k = \sum_{t=1}^{\ell} \delta(s_t = k)$ is the number of unique indices in $\{b_i\}_{i:z_i=k}$ and $n_{kt} = \delta(s_t = k) \sum_{i=1}^n \delta(b_i = t) = \sum_{i=1}^n \delta(b_i = t, z_i = k)$.

Simply applying the chain rule, we have

$$P(\mathbf{b}, \mathbf{z}, n | \mathbf{r}, p) = P(\mathbf{b}, \mathbf{z} | n, \mathbf{r}) \text{NB}(n; r., p) = \frac{1}{n!} \prod_{k=1}^K \left\{ r_k^{\ell_k} (1-p)^{r_k} p^{n_k} \prod_{t=1}^{\ell_k} \Gamma(n_{kt}) \right\}.$$

The mapping from $\{\mathbf{b}, \mathbf{z}, n\}$ to $\{\ell, \mathbf{n}, n\}$ is many to one, with

$$\begin{aligned} P(\ell, \mathbf{n}, n | \mathbf{r}, p) &= \prod_{k=1}^K \left\{ \sum_{(n_1, \dots, n_k) \in \mathcal{D}_{n_k, \ell_k}} \frac{1}{\ell_k! \prod_{t=1}^{\ell_k} n_{kt}!} r_k^{\ell_k} (1-p)^{r_k} p^{n_k} \prod_{t=1}^{\ell_k} \Gamma(n_{kt}) \right\} \\ &= \prod_{k=1}^K \left\{ r_k^{\ell_k} (1-p)^{r_k} p^{n_k} \frac{|s(n_k, \ell_k)|}{n_k!} \right\}, \end{aligned}$$

where $\mathcal{D}_{n_k, \ell_k} := \{(n_{k1}, \dots, n_{k\ell_k}) : n_{kt} \geq 1 \text{ and } \sum_{t=1}^{\ell_k} n_{kt} = n_k\}$. For (22), using the PMF of the Poisson-logarithmic bivariate distribution shown in (B.1), we have

$$P(\boldsymbol{\ell}, \mathbf{n}, n | \mathbf{r}, p) = \prod_{k=1}^K \left\{ r_k^{\ell_k} (1-p)^{r_k} p^{n_k} \frac{|s(n_k, \ell_k)|}{n_k!} \right\}.$$

□

Proof of Theorem 4. For the first hierarchical model, we have

$$\begin{aligned} P(\mathbf{n}, \boldsymbol{\ell} | n, \mathbf{r}) &= \left\{ \prod_{k=1}^K \text{CRT}(\ell_k; n_k, r_k) \right\} \text{DirMult}(\mathbf{n}; n, \mathbf{r}) \\ &= \frac{n!}{\prod_{k=1}^K n_k!} \frac{\Gamma(r.)}{\Gamma(n+r.)} \prod_{k=1}^K r_k^{\ell_k} |s(n_k, \ell_k)| \\ &= \frac{n!}{\prod_{k=1}^K \ell_k!} \frac{\Gamma(r.)}{\Gamma(n+r.)} \prod_{k=1}^K \left\{ r_k^{\ell_k} \sum_{(n_{k1}, \dots, n_{k\ell_k}) \in \mathcal{D}_{n_k, \ell_k}} \prod_{t=1}^{\ell_k} \frac{1}{n_{kt}} \right\}. \end{aligned}$$

Summing over all \mathbf{n} in the set $\mathcal{M}_{n,K} = \{(n_1, \dots, n_K) : n_k \geq 0 \text{ and } \sum_{k=1}^K n_k = n\}$, we have

$$\begin{aligned} P(\boldsymbol{\ell} | n, \mathbf{r}) &= \sum_{(n_1, \dots, n_K) \in \mathcal{M}_{n,K}} \frac{n!}{\prod_{k=1}^K \ell_k!} \frac{\Gamma(r.)}{\Gamma(n+r.)} \prod_{k=1}^K \left\{ r_k^{\ell_k} \sum_{(n_{k1}, \dots, n_{k\ell_k}) \in \mathcal{D}_{n_k, \ell_k}} \prod_{t=1}^{\ell_k} \frac{1}{n_{kt}} \right\} \\ &= \left\{ \frac{n!}{\prod_{k=1}^K \ell_k!} \frac{\Gamma(r.)}{\Gamma(n+r.)} \prod_{k=1}^K r_k^{\ell_k} \right\} \left\{ \sum_{(n_1, \dots, n_K) \in \mathcal{M}_{n,K}} \sum_{(n_{k1}, \dots, n_{k\ell_k}) \in \mathcal{D}_{n_k, \ell_k}} \prod_{t=1}^{\ell_k} \frac{1}{n_{kt}} \right\} \\ &= \left\{ \frac{n!}{\prod_{k=1}^K \ell_k!} \frac{\Gamma(r.)}{\Gamma(n+r.)} \prod_{k=1}^K r_k^{\ell_k} \right\} \left\{ \sum_{(n_1, \dots, n_{\ell.}) \in \mathcal{D}_{n, \ell.}} \prod_{t=1}^{\ell.} \frac{1}{n_t} \right\} \\ &= \frac{\ell.!}{\prod_{k=1}^K \ell_k!} \frac{\Gamma(r.)}{\Gamma(n+r.)} |s(n, \ell.)| \prod_{k=1}^K r_k^{\ell_k} \\ &= \text{Mult}(\boldsymbol{\ell}; \ell., r_1/r., \dots, r_K/r.) \text{CRT}(\boldsymbol{\ell}; n, r.). \end{aligned}$$

□

B Posterior analysis for the hGNBP

Denote $\ell \sim \text{CRT}(n, r)$ as the Chinese restaurant table (CRT) random variable generated as the summation of n independent Bernoulli random variables as $\ell = \sum_{i=1}^n h_i$, $h_i \sim$

Bernoulli $\left(\frac{r}{r+i-1}\right)$. The probability mass function (PMF) of $\ell \sim \text{CRT}(n, r)$ can be expressed as $f_L(\ell | n, r) = \frac{\Gamma(r)r^\ell}{\Gamma(n+r)} |s(n, \ell)|$, where $\ell \in \{0, 1, \dots, n\}$ and

$$|s(n, \ell)| = \frac{n!}{\ell!} \sum_{(n_1, \dots, n_\ell) \in \mathcal{D}_{n, \ell}} \prod_{t=1}^{\ell} \frac{1}{n_t}$$

are unsigned Stirling numbers of the first kind (Johnson et al. 1997) that can be obtained by summing over the elements of the set $\mathcal{D}_{n, \ell} = \{(n_1, \dots, n_\ell) : n_t \geq 1 \text{ and } \sum_{t=1}^{\ell} n_t = n\}$.

Let $u \sim \text{Logarithmic}(p)$ denote the logarithmic distribution (Fisher et al. 1943) with PMF $f_U(u | p) = \frac{1}{-\ln(1-p)} \frac{p^u}{u}$, where $u \in \{1, 2, \dots\}$. Denote $x \sim \text{SumLog}(\ell, p)$ as the sum-logarithmic random variable (Zhou et al. 2016b) generated as $x = \sum_{t=1}^{\ell} u_t$, $u_t \sim \text{Logarithmic}(p)$, with PMF $f_N(n | \ell, p) = \frac{p^n \ell! |s(n, \ell)|}{n! [-\ln(1-p)]^\ell}$. As revealed in Zhou and Carin (2015), the joint distribution of n and ℓ given r and p in $\ell | n \sim \text{CRT}(n, r)$, $n \sim \text{NB}(r, p)$ is the same as that in $n | \ell \sim \text{SumLog}(\ell, p)$, $\ell \sim \text{Pois}[-r \ln(1-p)]$, which is called as the Poisson-logarithmic bivariate distribution, with PMF

$$f_{N,L}(n, \ell | r, p) = \frac{|s(n, \ell)| r^\ell}{n!} p^n (1-p)^r. \quad (\text{B.1})$$

Denote $L \sim \text{CRTP}(X, G)$ as a CRT process such that $L(A) = \sum_{\omega \in A} L(\omega)$, $L(\omega) \sim \text{CRT}[X(\omega), G(\omega)]$ for each $A \subset \Omega$, and $X \sim \text{SumLogP}(L, p)$ as a sum-logarithmic process such that $X(A) \sim \text{SumLog}[L(A), p]$ for each $A \subset \Omega$. As in Zhou and Carin (2015), generalizing the Poisson-logarithmic bivariate distribution, one may show that X and L given G and p in

$$L | X \sim \text{CRTP}(X, G), \quad X \sim \text{NBP}(G, p)$$

is equivalent in distribution to those in

$$X | L \sim \text{SumLogP}(L, p), \quad L \sim \text{PP}[-G \ln(1-p)],$$

where $L \sim \text{PP}[-G \ln(1-p)]$ is a Poisson process such that $L(A) \sim \text{Pois}[-G(A) \ln(1-p)]$ for each $A \subset \Omega$. Generalizing the analysis for the GNB in Zhou and Carin (2015) and Zhou et al. (2016b), with

$$\tilde{p}_j := \frac{-\ln(1-p_j)}{c_j - \ln(1-p_j)}, \quad \tilde{p} := \frac{-\sum_j \ln(1-\tilde{p}_j)}{c_0 - \sum_j \ln(1-\tilde{p}_j)},$$

we can express the conditional posteriors of G and Θ_j as

$$\begin{aligned} (L_j | X_j, \Theta_j) &\sim \text{CRTP}(X_j, \Theta_j), \quad (\tilde{L}_j | L_j, G) \sim \text{CRTP}(L_j, G), \\ (G | \{\tilde{L}_j, p_j\}_j, G_0) &\sim \text{GP}\left(G_0 + \sum_j \tilde{L}_j, [c_0 - \sum_j \ln(1-\tilde{p}_j)]^{-1}\right), \\ (\Theta_j | G, \tilde{L}_j, p_j, c_j) &\sim \text{GP}\left(G + L_j, [c_j - \ln(1-p_j)]^{-1}\right). \end{aligned} \quad (\text{B.2})$$

If we let $\gamma_0 \sim \text{Gamma}(a_0, 1/b_0)$, the conditional posterior of γ_0 can be expressed as

$$\begin{aligned} (\tilde{L} | \{\tilde{L}_j\}_j, G_0) &\sim \text{CRTP}(\sum_j \tilde{L}_j, G_0), \\ (\gamma_0 | \tilde{L}, \{p_j, c_j\}_j, c_0) &\sim \text{Gamma}\left(a_0 + \tilde{L}(\Omega), [b_0 - \ln(1 - \tilde{p})]^{-1}\right). \end{aligned}$$

If the base measure G_0 is finite and continuous, we have

$$\tilde{L}(\Omega) = \sum_{k=1}^{\infty} \delta\left(\sum_j \tilde{L}_j(\phi_k) > 0\right) = \sum_{k=1}^{\infty} \delta\left(\sum_j X_j(\phi_k) > 0\right),$$

which is the number of active atoms that are associated with nonzero counts, otherwise we have $(\tilde{L}(\omega_k) | \{\tilde{L}_j\}_j, G_0) \sim \text{CRT}[\sum_j \tilde{L}_j(\omega_k), G_0(\omega_k)]$ for all atoms $\omega_k \in \Omega$. In this paper, we let $K^+ = \tilde{L}(\Omega)$ denote the number of active atoms.

C Additional Gibbs sampling update equations

Algorithm 1 Gibbs sampling algorithms for the hierarchical gamma-negative binomial process negative binomial factor analysis (Dirichlet-multinomial mixed-membership model).

```

1: for iter = 1 : MaxIter do Gibbs sampling
2:   switch Gibbs sampler do
3:     case regular blocked Gibbs sampler
4:       sample  $\{z_{ji}\}_{j,i}$  and then calculate  $\{n_{vjk}\}_{v,j,k}$ ;
       sample a latent count  $\ell_{vjk}$  for each  $n_{vjk}$ ;
5:     case collapsed Gibbs sampler
6:       sample  $\{z_{ji}, b_{ji}\}_{j,i}$  and then calculate  $\{n_{vjk}, \ell_{vjk}\}_{v,j,k}$ ;
7:     case compound Poisson based blocked Gibbs sampler
8:       sample a latent count  $\ell_{vj}$  for each  $n_{vj}$ ; sample  $\{\ell_{vjk}\}_k$  for each  $\ell_{vj}$ ;
9:   end switch
10:  sample  $\{p_j\}_j$ ; sample  $\{c_j\}_j$ ; sample  $\gamma_0$ ; sample  $c_0$ ; relabel the active factors
    from 1 to  $K^+$ .
11:  if collapsed Gibbs sampler then
12:    sample  $\{r_k\}_{1, K^+}$ ; sample  $r_*$ ; sample  $\{\theta_{\cdot j}\}_j$ ;
13:  else
14:    for  $k = 1 : K^+ + K_*$  do
15:      sample  $\phi_k^{(t)}$ ; sample  $r_k$ ; sample  $\{\theta_{kj}\}_j$ ;
16:    end for
17:  end if
18: end for

```

C.1 Additional update equations for blocked Gibbs sampling

Sample p_j . We sample p_j as

$$(p_j | -) \sim \text{Beta}(a_0 + n_j, b_0 + \theta_{\cdot j}). \quad (\text{C.1})$$

Sample c_j . We sample c_j as

$$(c_j | -) \sim \text{Gamma}[e_0 + G(\Omega), 1/(f_0 + \theta_{\cdot j})].$$

Sample r_k . We first sample latent counts and then sample γ_0 and c_0 as

$$\begin{aligned} (\tilde{\ell}_{jk} | -) &\sim \text{CRT}(\ell_{\cdot jk}, r_k), \quad (\gamma_0 | -) \sim \text{Gamma}\left(a_0 + K^+, \frac{1}{b_0 - \ln(1 - \tilde{p})}\right), \\ (c_0 | -) &\sim \text{Gamma}\left(e_0 + \gamma_0, \frac{1}{f_0 + G(\Omega)}\right), \end{aligned}$$

where $\tilde{\ell}_{\cdot k} := \sum_j \tilde{\ell}_{jk}$, $K^+ := \sum_k \delta(n_{\cdot k} > 0) = \sum_k \delta(\tilde{\ell}_{\cdot k} > 0)$. For all the points of discontinuity, *i.e.*, the factors in the set $\{\phi_k\}_{k:n_{\cdot k} > 0}$, we relabel their indices from 1 to K^+ and then sample r_k as

$$(r_k | -) \sim \text{Gamma}\left(\tilde{\ell}_{\cdot k}, \frac{1}{c_0 - \sum_j \ln(1 - \tilde{p}_j)}\right),$$

and for the absolutely continuous space $\{\phi_k\}_{k:n_{\cdot k} = 0}$, we draw K_\star unused atoms, whose weights are sampled as

$$(r_k | -) \sim \text{Gamma}\left(\frac{\gamma_0}{K_\star}, \frac{1}{c_0 - \sum_j \ln(1 - \tilde{p}_j)}\right).$$

We let $K := K^+ + K_\star$ and $G(\Omega) := \sum_{k=1}^K r_k$.

Sample ϕ_k . Denote $\ell_{v \cdot k} = \sum_{j=1}^J \ell_{vjk}$. Since $\ell_{vjk} \sim \text{Pois}[-\phi_{vk} \theta_{kj} \ln(1 - p_j)]$ in the prior, we can sample ϕ_k as

$$(\phi_k | -) \sim \text{Dir}(\eta + \ell_{1 \cdot k}, \dots, \eta + \ell_{V \cdot k}).$$

Sample θ_{kj} . Denote $\ell_{\cdot jk} = \sum_{v=1}^V \ell_{vjk}$. We can sample θ_{kj} as

$$(\theta_{kj} | -) \sim \text{Gamma}\left(r_k + \ell_{\cdot jk}, \frac{1}{c_j - \ln(1 - p_j)}\right). \quad (\text{C.2})$$

C.2 Additional update equations for collapsed Gibbs sampling

The other model parameters can all be sampled in the way similar to how they are sampled in Section 5.1. Below we highlight the differences. First, we do not need to sample $\{\phi_k\}$. Instead of sampling $\{\theta_{kj}\}_k$, we only need to sample $\theta_{\cdot j}$ as

$$(\theta_{\cdot j} | -) \sim \text{Gamma}[G(\Omega) + \sum_k \ell_{\cdot j k}, 1/(c_j - \ln(1 - p_j))].$$

For the absolutely continuous space, we have

$$(r_{\star} | -) \sim \text{Gamma}\left(\gamma_0, \frac{1}{c_0 - \sum_j \ln(1 - \tilde{p}_j)}\right).$$

We have $K^+ = \sum_k \delta(\ell_{\cdot k} > 0)$ and $G(\Omega) := r_{\star} + \sum_{k: \ell_{\cdot k} > 0} r_k$.

D Gamma-negative binomial process PFA and DCMLDA

We consider the GNBP (Zhou and Carin 2015) as

$$X_j \sim \text{NBP}(G, p_j), \quad G \sim \text{FP}(G_0, 1/c_0). \quad (\text{D.1})$$

The GNBP multinomial mixed-membership model of Zhou and Carin (2015) can be expressed as

$$\begin{aligned} x_{ji} &\sim \text{Cat}(\phi_{z_{ji}}), \quad z_{ji} \sim \text{Cat}(\theta_j/\theta_{\cdot j}), \\ \theta_{kj} &\sim \text{Gamma}[r_k, p_j/(1 - p_j)], \\ n_j &\sim \text{Pois}(\theta_{\cdot j}), \quad p_j \sim \text{Beta}(a_0, b_0), \\ G &\sim \text{FP}(G_0, 1/c_0), \end{aligned}$$

which, as far as the conditional posteriors of $\{\phi_k\}_k$ and $\{\theta_j\}_j$ are concerned, can be equivalently represented as the GNBP-PFA

$$\begin{aligned} n_{vj} &= \sum_{k=1}^{\infty} n_{vjk}, \quad n_{vjk} \sim \text{Pois}(\phi_{vk}\theta_{kj}), \\ \theta_{kj} &\sim \text{Gamma}[r_k, p_j/(1 - p_j)], \\ p_j &\sim \text{Beta}(a_0, b_0), \quad G \sim \text{FP}(G_0, 1/c_0). \end{aligned}$$

Similar to how adaptive truncation is used in blocked Gibbs sampling for the hGNBP-NBFA, one may readily extend the blocked Gibbs sampler for the GNBP multinomial mixed-membership model developed in Zhou and Carin (2015), which has a fixed finite truncation, to a one with adaptive truncation. We omit these details for brevity. We describe a collapsed Gibbs sampler for the GNBP-PFA in Appendix D.1.

As discussed before, the GNBP can also be applied to DCMLDA to support countably infinite factors. We express the GNBP-DCMLDA as

$$\begin{aligned} x_{ji} &\sim \text{Cat}(\phi_{z_{ji}}^{[j]}), \quad z_{ji} \sim \text{Cat}(\theta_j), \\ \phi_k^{[j]} &\sim \text{Dir}(\phi_k r_k), \quad \theta_j \sim \text{Dir}(\mathbf{r}), \\ n_j &\sim \text{NB}(r_{\cdot}, p_j), \quad p_j \sim \text{Beta}(a_0, b_0), \\ G &\sim \text{FP}(G_0, 1/c_0), \end{aligned} \quad (\text{D.2})$$

which, as far as the conditional posteriors of $\{\phi_k\}_k$ and $\{r_k\}_k$ are concerned, can be equivalently represented as

$$\begin{aligned}
n_{vj} &= \sum_{k=1}^{\infty} n_{vjk}, \quad n_{vjk} \sim \text{NB}(\phi_{vk} r_k, p_j). \\
p_j &\sim \text{Beta}(a_0, b_0), \quad G \sim \text{GP}(G_0, 1/c_0).
\end{aligned} \tag{D.3}$$

The restriction is evident from (D.3) as all the samples are enforced to have the same factor scores as \mathbf{r}_k under the shared factors $\{\phi_k\}_k$. Blocked Gibbs sampling with and without sampling z_{ji} for the GNB-DCMLDA can be similarly derived as those for the hGNBP DMMM model, omitted here for brevity. We describe in detail a collapsed Gibbs sampler for the GNB-DCMLDA in Appendix D.2.

D.1 Collapsed Gibbs sampling for GNB-PFA

For the GNB in (D.1), the conditional likelihood $p(\{X_j\}_{1,J} | G)$ is shown in Appendix B.1 of Zhou et al. (2016b). As there is a one-to-many mapping from $\{X_j\}_{1,J}$ to $\mathbf{z} = \{z_{11}, \dots, z_{Jm_J}\}$, similar to the analysis in Zhou (2014), we have the joint likelihood of \mathbf{z} and the sample lengths $\mathbf{m} = (m_1, \dots, m_J)$ as

$$p(\mathbf{z}, \mathbf{m} | G, \mathbf{p}) = \frac{p(\{X_j\}_{1,J} | G)}{\prod_{j=1}^J \frac{n_j!}{\prod_{k=1}^{\infty} n_{jk}!}} = \prod_{j=1}^J \frac{p_j^{n_j}}{n_j!} \prod_{k=1}^{\infty} \frac{\Gamma(n_{jk} + r_k)}{\Gamma(r_k)} (1 - p_j)^{r_k}.$$

Assuming the K^+ factors that are associated with nonzero counts are relabeled in an arbitrary order from 1 to K^+ , based on this conditional likelihood, we have a prediction rule conditioning on G as

$$P(z_{ji} = k | \mathbf{z}^{-ji}, \mathbf{m}, G) \propto \begin{cases} n_{jk}^{-ji} + r_k, & \text{for } k = 1, \dots, (K^+)^{-ji}, \\ r_*, & \text{if } k = (K^+)^{-ji} + 1, \end{cases}$$

where $r_* = G(\Omega \setminus \{\phi_k\}_{1,K^+})$ is the total weight of all the factors assigned with zero count. This prediction rule becomes very similar to the direct assignment sampler of the hierarchical Dirichlet process (Teh et al. 2006) if one writes each r_k as the product of a total random mass α and a probability π_k , with $\alpha = \sum_{k=1}^{\infty} r_k$ and $\sum_{k=1}^{\infty} \pi_k = 1$. This is as expected since the gamma process can be represented as the independent product of a gamma process and a Dirichlet process, under the condition that the mass parameter of the gamma process is the same as the concentration parameter of the Dirichlet process, and the GNB is closely related to the hierarchical Dirichlet process for mixed-membership modeling (Zhou and Carin 2015).

Similar to the derivation of collapsed Gibbs sampling for the mixed-membership model based on the beta-negative binomial process, as shown in Zhou (2014), we can write the collapsed Gibbs sampling update equation for the factor indices as

$$P(z_{ji} = k | \mathbf{x}, \mathbf{z}^{-ji}, \mathbf{m}, G) \propto \begin{cases} \frac{\eta + n_{v_{ji},k}^{-ji}}{V\eta + n_{\cdot,k}^{-ji}} \cdot (n_{jk}^{-ji} + r_k), & \text{for } k = 1, \dots, (K^+)^{-ji}; \\ \frac{1}{V} \cdot r_*, & \text{if } k = (K^+)^{-ji} + 1; \end{cases}$$

and if $k = (K^+)^{-ji} + 1$ happens, we draw $\beta \sim \text{Beta}(1, \gamma_0)$ and then let $r_k = \beta r_\star$ and $r_\star = (1 - \beta)r_\star$. Gibbs sampling update equations for the other model parameters of the GNBP can be similarly derived as in Zhou and Carin (2015) and Zhou et al. (2016b), omitted here for brevity.

D.2 Collapsed Gibbs sampling for GNBP-DCMLDA

For collapsed Gibbs sampling of (D.2), introducing the auxiliary variables

$$\{b_{ji}\}_{i:x_{ji}=v, z_{ji}=k} \sim \text{CRP}(n_{vjk}, \phi_{vk} r_k),$$

we have the joint likelihood of $\mathbf{b}_j, \mathbf{z}_j, \mathbf{x}_j$ and n_j for DCMLDA as

$$P(\mathbf{b}_j, \mathbf{x}_j, \mathbf{z}_j, n_j | \Phi, \theta_j, p_j) = \frac{1}{n_j!} \prod_v \prod_k \left\{ (\phi_{vk} r_k)^{\ell_{vjk}} p_j^{n_{vjk}} (1 - p_j)^{\phi_{vk} r_k} \prod_{t=1}^{\ell_{vjk}} \Gamma(n_{vjkt}) \right\},$$

where ℓ_{vjk} is the number of unique indices in $\{b_{ji}\}_{i:x_{ji}=v, z_{ji}=k}$ and $n_{vjkt} = \sum_{i=1}^{n_j} \delta(x_{ji} = v, z_{ji} = k, b_{ji} = t)$.

Marginalizing out Φ from this likelihood, we have

$$\begin{aligned} P(\{\mathbf{b}_j, \mathbf{x}_j, \mathbf{z}_j, n_j\}_j | G, \mathbf{p}) &= e^{r_\star \sum_j \ln(1-p_j)} \left\{ \prod_j p_j^{n_j} \frac{\prod_v \prod_k \left(\prod_{t=1}^{\ell_{vjk}} \Gamma(n_{vjkt}) \right)}{n_j!} \right\} \\ &\times \left\{ \prod_{k:\ell_{..k}>0} r_k^{\ell_{..k}} e^{r_k \sum_j \ln(1-p_j)} \frac{\Gamma(V\eta)}{\Gamma(\ell_{..k} + V\eta)} \prod_{v=1}^V \frac{\Gamma(\ell_{v..k} + \eta)}{\Gamma(\eta)} \right\}, \end{aligned} \quad (\text{D.4})$$

where $r_\star := \sum_{k:\ell_{..k}=0} r_k$. With this likelihood, we have

$$P(z_{ji} = k, b_{ji} = t | x_{ji}, \mathbf{z}^{-ji}, \mathbf{b}^{-ji}, G) \propto \begin{cases} n_{x_{ji}jkt}^{-ji}, & \text{if } k \leq (K^+)^{-ji}, t \leq \ell_{x_{ji}jkt}^{-ji}; \\ \frac{\ell_{x_{ji}.k}^{-ji} + \eta}{\ell_{..k}^{-ji} + V\eta} r_k, & \text{if } k \leq (K^+)^{-ji}, t = \ell_{x_{ji}jkt}^{-ji} + 1; \\ \frac{r_\star}{V}, & \text{if } k = (K^+)^{-ji} + 1, t = 1; \end{cases}$$

and if $k = (K^+)^{-ji} + 1$ happens, then we draw then we draw $\beta \sim \text{Beta}(1, \gamma_0)$ and then let $r_k = \beta r_\star$ and $r_\star = (1 - \beta)r_\star$.

Using the Palm formula (James 2002; James et al. 2009; Caron et al. 2014), similar to related derivation in Zhou et al. (2016b), we may further marginalize out G from

(D.4), leading to

$$\begin{aligned}
& P(\{\mathbf{b}_j, \mathbf{x}_j, \mathbf{z}_j, n_j\}_j \mid \gamma_0, c_0, \mathbf{p}) \\
&= \gamma_0^{K^+} e^{-\ln\left(\frac{c_0 - \sum_j \ln(1-p_j)}{c_0}\right)} \left\{ \prod_j p_j^{n_j} \frac{\prod_v \prod_k \left(\prod_{t=1}^{\ell_{vjk}} \Gamma(n_{vjk} t) \right)}{n_j!} \right\} \\
&\quad \times \left\{ \prod_{k: \ell_{..k} > 0} \frac{\Gamma(\ell_{..k})}{[c_0 - \sum_j \ln(1-p_j)]^{\ell_{..k}}} \frac{\Gamma(V\eta)}{\Gamma(\ell_{..k} + V\eta)} \prod_{v=1}^V \frac{\Gamma(\ell_{v..k} + \eta)}{\Gamma(\eta)} \right\},
\end{aligned}$$

with which we have

$$\begin{aligned}
& P(z_{ji} = k, b_{ji} = t \mid x_{ji}, \mathbf{z}^{-ji}, \mathbf{b}^{-ji}, \gamma_0, c_0) \\
&\propto \begin{cases} n_{x_{ji}jk}^{-ji}, & \text{if } k \leq (K^+)^{-ji}, t \leq \ell_{x_{ji}jk}^{-ji}; \\ \frac{\ell_{x_{ji}k}^{-ji} + \eta}{\ell_{..k}^{-ji} + V\eta} \frac{\ell_{..k}^{-ji}}{c_0 - \sum_j \ln(1-p_j)}, & \text{if } k \leq (K^+)^{-ji}, t = \ell_{x_{ji}jk}^{-ji} + 1; \\ \frac{1}{V} \frac{\gamma_0}{c_0 - \sum_j \ln(1-p_j)}, & \text{if } k = (K^+)^{-ji} + 1, t = 1. \end{cases}
\end{aligned}$$

We use the above equation in the collapsed Gibbs sampler for GNBP-DCMLDA.

E Sample the Dirichlet smoothing parameter

For the hGNBP-NBFA, from (24), we have the likelihood for $\{\phi_k\}$ as

$$\mathcal{L}(\{\phi_k\}) \propto \prod_k \text{Mult}(\ell_{1..k}, \dots, \ell_{V..k}; \ell_{..k}, \phi_k) \quad (\text{E.1})$$

Marginalizing out ϕ_k from (E.1), we have the likelihood for η as

$$\mathcal{L}(\eta) \propto \prod_k \text{DirMult}(\ell_{1..k}, \dots, \ell_{V..k}; \ell_{..k}, \eta, \dots, \eta).$$

Since the product of $\mathcal{L}(\eta)$ and $\prod_k \text{Beta}(q_k; \ell_{..k}, \eta V)$ can be expressed as

$$\mathcal{L}(\eta) \prod_k \text{Beta}(q_k; \ell_{..k}, \eta V) \propto \prod_k \prod_v \text{NB}(\ell_{v..k}; \eta, q_k),$$

we can further apply the data augmentation technique for the NB distribution of Zhou and Carin (2015) to derive closed-form update equations for η as

$$\begin{aligned}
& (q_k \mid -) \sim \text{Beta}(\ell_{..k}, V\eta), \quad (t_{vk} \mid -) \sim \text{CRT}(\ell_{v..k}, \eta), \\
& (\eta \mid -) \sim \text{Gamma} \left(a_0 + \sum_{v=1}^V \sum_{k=1}^{K^+} t_{vk}, \frac{1}{b_0 - V \sum_{k=1}^{K^+} \ln(1-q_k)} \right) \quad (\text{E.2})
\end{aligned}$$

To sample η for the GNBP-PFA, we simply replace $\ell_{..k}$ and $\ell_{v.k}$ in (E.2) with $n_{..k}$ and $n_{v.k}$, respectively. We note the inference of η for the GNBP-PFA can be related to the inference of that for LDA described in Newman et al. (2009).

F Comparisons of different sampling strategies

We first diagnose the convergence of the regular blocked Gibbs sampler in Section 5.1, the collapsed Gibbs sampler in Section 5.2, and the compound Poisson representation based blocked Gibbs sampler in Section 5.3 for the hGNBP-NBFA (Dirichlet-multinomial mixed-membership model), via the trace plots of the inferred number of active factors K^+ . We set the Dirichlet smoothing parameter as $\eta = 0.05$, and initialize the number of factors as $K = 0$ for the collapsed Gibbs sampler and $K = 10$ for both the regular and compound Poisson based blocked Gibbs samplers. We also consider initializing the number of factors as $K = 500$ for all three samplers.

As shown in Figure 7 for the PsyReview dataset, both the regular blocked Gibbs sampler and collapsed Gibbs sampler travel relatively slowly to the target distribution of the number of active factors K^+ , especially when the number of factors is initialized to be large, whereas the compound Poisson based blocked Gibbs sampler travels relatively quickly to the target distribution in both cases. We have also made similar comparisons on both the JACM and NIPS12 datasets, and the experiments on all three datasets consistently suggest that the compound Poisson representation based blocked Gibbs sampler converges the fastest in the number of inferred active factors.

We observe similar differences in convergence between the blocked Gibbs sampler, the collapsed Gibbs sampler, and the compound Poisson representation based blocked Gibbs sampler for the GNBP-DCMLDA. This is as expected since GNBP-DCMLDA can be considered as a special case of the hGNBP-NBFA, and its compound Poisson representation also allows it to eliminate the need of sampling the factor indices $\{z_{ji}\}$.

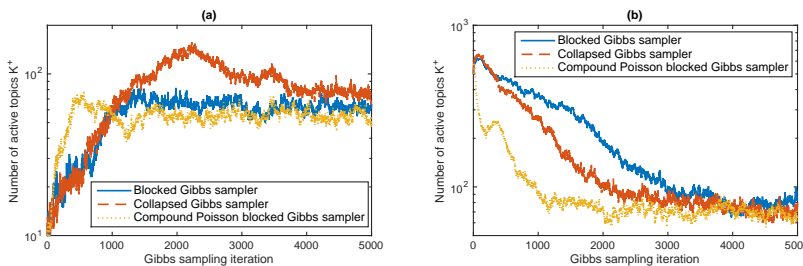


Figure 7: Comparison of three different Gibbs samplers for the hierarchical gamma-negative binomial process negative binomial factor analysis (hGNBP-NBFA) on the PsyReview dataset, with the number of factors initialized as (a) $K = 0$ for the collapsed sampler and $K = 10$ for both blocked samplers, and (b) $K = 500$ for all three samplers. In each plot, the blue, red, and yellow curves correspond to the active number of factors as a function of Gibbs sampling iteration for the regular blocked Gibbs sampler, the collapsed Gibbs sampler, and the compound Poisson representation based blocked Gibbs sampler, respectively.

For the GNB-PFA, we find that its blocked Gibbs sampler, presented in Zhou and Carin (2015) and improved in this paper to allow adaptively truncating the number of active factors in each Gibbs sampling iteration, could converge slightly faster if the number of factors is initialized to be large. However, its collapsed Gibbs sampler shown in the Appendix often converges much faster in the number of inferred active factors if the number of factors is initialized with a small value.

Therefore, to learn the factors in all the following experiments, we use the compound Poisson representation based blocked Gibbs sampler for both the hGNBP-NBFA and GNB-NBFA, and use collapsed Gibbs sampling for the GNB-PFA.

G Additional table and plots

Table 3: Datasets used in experiments.

	JACM	PsyReview	NIPS12	<i>atheism vs religion</i>	<i>pc vs mac</i>	20 news groups
Number of unique covariates V	1,539	2,566	13,649	6,509	4,737	33,420
Number of samples	536	1,281	1,740	856	1,162	11,269
Total number of covariate indices	68,055	71,279	2,301,375	115,904	90,667	1,424,713
Average sample length	127	56	1,323	135	78	126

We show the results of the GNB-NBFA, GNB-DCMLDA, and hGNBP-NBFA on both the PsyReview and JACM datasets in the following figures.

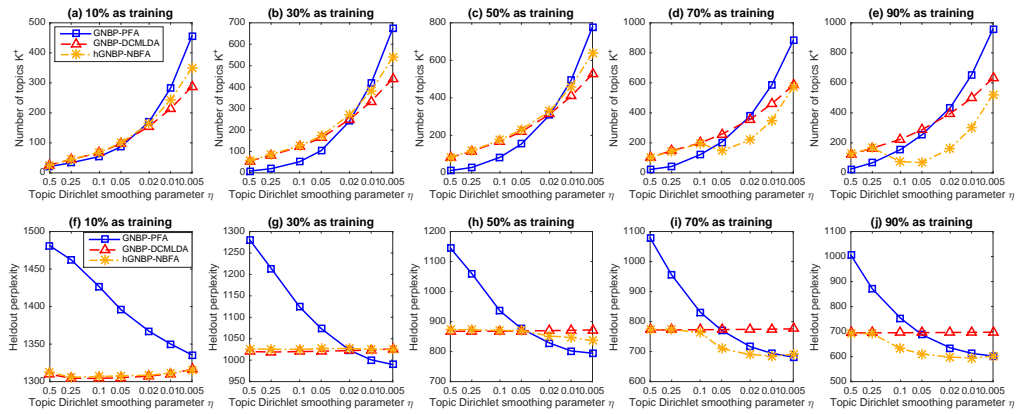


Figure 8: Analogous plots to those in Figure 2 for the PsyReview dataset.

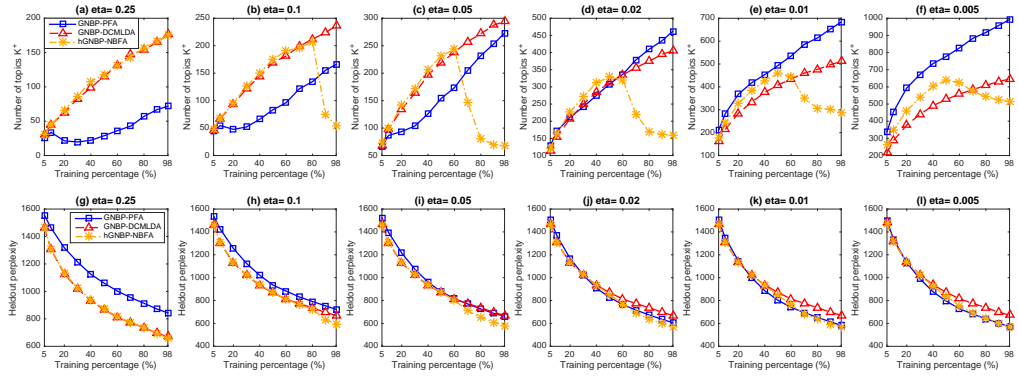


Figure 9: Analogous plots to those in Figure 4 for the PsyReview dataset.

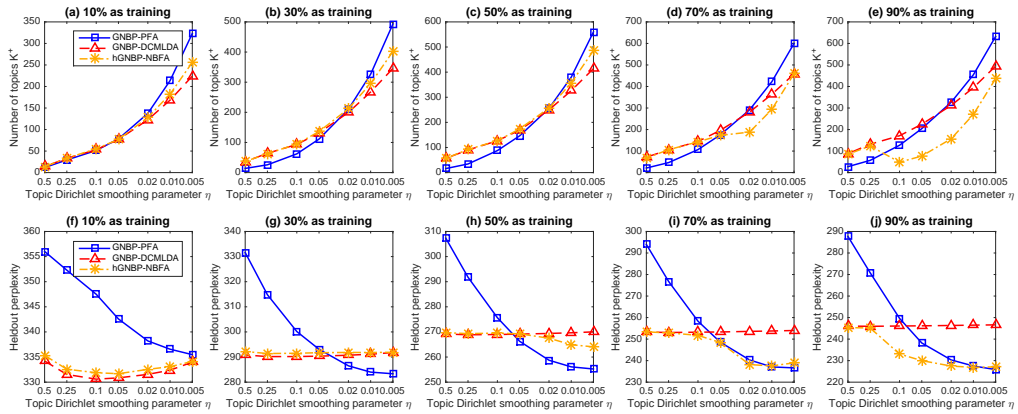


Figure 10: Analogous plots to those in Figure 2 for the JACM dataset.

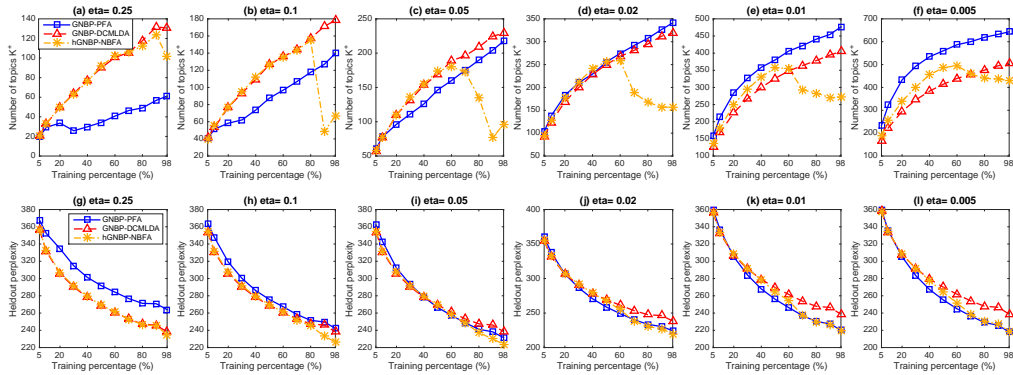


Figure 11: Analogous plots to those in Figure 4 for the JACM dataset.